

Section A

1(a) Prove that a finite integral domain is a field

(10)

Let R is a finite integral domain
 $\Rightarrow R$ is commutative and unity ring
 and R has no zero divisor

To Prove, R as field we need to
 Prove that every non zero element of
 R has its inverse in R

Now, since R is finite, let

$$\Rightarrow R = \{a_1, a_2, a_3, \dots, a_n\}$$

all a_i are distinct

if $\exists a \in R, a \neq 0$

$$\Rightarrow R = \{aa_1, aa_2, aa_3, \dots, aa_n\} \quad \text{--- ①}$$

here all aa_i are distinct

because if $aa_i = aa_r$

$$\Rightarrow a(a_i - a_r) = 0$$

since no zero divisor

$$\Rightarrow a_i - a_r = 0 = a_i = a_r$$

which is not possible

\Rightarrow any one of set ①, such must
 be equal to unity

let
 $\Rightarrow aa_i = 1$

$\Rightarrow a_i$ is inverse of a

\therefore every non zero element has
 its inverse

$$\Rightarrow \boxed{R \text{ is a field}}$$



1(b) Prove that if an ideal U of a ring R contains a unit of R , then $U = R$. (10)

Let a is unit in R
and given $a \in U$

$\therefore a$ is unit in R

$\Rightarrow \exists b \in R$ such that
 $a \cdot b = 1$ — (1)

Now since $a \in U, b \in R$

$\Rightarrow a \cdot b \in U$ as U is an ideal

$\Rightarrow 1 \in U$

Since unity of R belongs to U

\Rightarrow if $x \in R$

$\Rightarrow x \cdot 1 \in U$ (U is ideal)

$\Rightarrow x \in U$

$\Rightarrow R \subseteq U$ — (2)

Since U is ideal of R

$\Rightarrow U \subseteq R$ — (3)

From (2) & (3)

$U = R$

Q

1(c) Show that $\int_0^{\pi/2} x^m \operatorname{cosec}^n x dx$ exists iff $n < (m+1)$

$$I = \int_0^{\pi/2} x^m \operatorname{cosec}^n x dx$$

$$I = \int_0^{\pi/2} \frac{x^m}{\sin^n x} dx$$

at $x \rightarrow \frac{\pi}{2}$, $\frac{x^m}{\sin^n x}$ has finite value irrespective of value of m and n

$\therefore \frac{\pi}{2}$ is not point of discontinuity

Convergence at $x=0$ \rightarrow

$$\int_0^{\pi/2} \frac{x^m}{\sin^n x} = \int_0^{\pi/2} \frac{x^n}{(\sin^n x)} \cdot x^{m-n}$$

• let $f(x) = \frac{x^n \cdot x^{m-n}}{(\sin^n x)}$

$$g(x) = \frac{1}{x^{n-m}}$$

$$\lim_{x \rightarrow 0} \frac{f(x)}{g(x)} = \lim_{x \rightarrow 0} \frac{x^n \cdot x^{m-n}}{\sin^n x \cdot x^{m-n}} = 1$$

$\therefore \int_0^a f(x) dx$ & $\int_0^a g(x) dx$ Converges & diverges together)

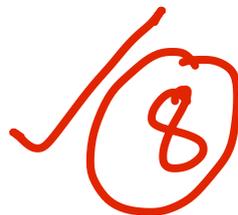
(from ~~rule~~)

now, $\int_0^a \frac{1}{x^{n-m}} dx$ will converge iff

$$n-m < 1$$

$$\Rightarrow n < m+1$$

$\therefore \int_0^{\pi/2} \frac{x^m}{\sin^n x} dx = \int_0^{\pi/2} x^m \operatorname{cosec}^n x$ will converge iff $n < (m+1)$

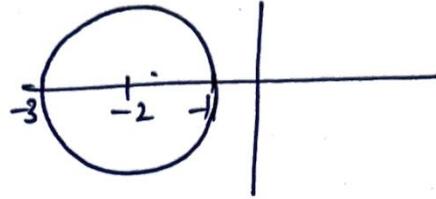


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1(d) Evaluate $\int_C \frac{e^{-2z} z^2}{(z-1)^3(z+2)} dz$ where C is $|z+2|=1$ using Cauchy's integral (10)

given $|z+2|=1$

$$\int_C \frac{e^{-2z} z^2}{(z-1)^3(z+2)} dz$$



Cauchy's integral formula

$$f(z_0) = \frac{1}{2\pi i} \int_C \frac{f(z)}{(z-z_0)} dz$$

where z_0 is only singularity

$f(z)$ has no singular point in $C \rightarrow C$

& $f(z)$ is analytic in C

here consider, $f(z) = \frac{e^{-2z} z^2}{(z-1)^3}$ and $z_0 = -2$

$\Rightarrow f(z)$ is analytic in C

$$f(-2) = \frac{e^4 \cdot 2^2}{(-3)^3} = \frac{4e^4}{-27}$$

$$\therefore \int_C \frac{f(z)}{(z-z_0)} dz = 2\pi i \times \frac{4e^4}{-27}$$

$$\therefore \int_C \frac{e^{-2z} z^2}{(z-1)^3(z+2)} dz = -\frac{8\pi i}{27} e^4$$

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1(e) Solve the following transportation problem by Vogel's approximation method

		To					Supply ↓
		W_1	W_2	W_3	W_4	W_5	
From	F_1	3	4	6	8	9	20
	F_2	2	10	1	5	8	30
	F_3	7	11	20	40	3	15
	F_4	2	1	9	14	16	13
Demand →		40	6	8	18	6	

For initial Balm's feasible solution

3) <u>20</u>	4) ρ	6) ρ	8) ρ	9) ρ	20 (1) (5)
2) <u>4</u>	10) ρ	1) <u>8</u>	5) <u>18</u>	8) ρ	30 (15) (9) 22
7) <u>9</u>	11) ρ	20) ρ	40) ρ	3) <u>6</u>	15 (4)
2) <u>7</u>	1) <u>6</u>	9) ρ	14) ρ	16) ρ	13 (4) (2)
45	8	8	18	6	79
24	27	35	5	5	
4	(1)		(3)	(5)	

Initial solution now u-v method

3) <u>20</u>	4) (-)	6) (-)	8) (-)	9) (-)	(3)
2) <u>4</u>	(-)	8) <u>8</u>	5) <u>18</u>	8) (-)	(2)
7) <u>9</u>	(-)	20) ρ	40) ρ	3) <u>6</u>	(7)
2) <u>7</u>	1) <u>6</u>	9) (-)	14) (-)	16) (-)	(2)
v_j (0)	(-1)	(1)	(3)	(-4)	

as all $u_i + v_j - c_{ij}$ are negative
thus optimal has reached

$$\Rightarrow \text{Cost} = \underline{20 \times 3} + \underline{2 \times 4} + \underline{7 \times 9} + \underline{2 \times 7} + \underline{1 \times 8} + \underline{5 \times 18} + \underline{6 \times 1} + \underline{3 \times 6}$$

$$\boxed{\text{Cost} = 267}$$

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	w_1	w_2	w_3	w_4	w_5	
F_1	(20)					20
F_2	(4)		(8)	(18)		30
F_3	(9)				(6)	15
F_4	(7)	(6)				13
	40	6	8	18	6	

SuccessClap

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3(a) Let $f(x,y) = \begin{cases} x^2 y^2 \cos \frac{1}{x} & , \text{ for all values of } y \text{ so long as } x \neq 0 \\ 0 & , \text{ for } x = 0 \end{cases}$

Show that

(i) $f_{xy} = f_{yx}$ at all points (x,y) ,

(ii) neither f_{xy} nor f_{yx} is continuous in x at $x = 0$, if $y \neq 0$.

and (iii) both f_{xy} and f_{yx} are continuous in (x,y) , together at the origin.

(20)

$$f(x,y) = \begin{cases} x^2 y^2 \cos \frac{1}{x} & \text{otherwise} \\ 0 & x=0 \end{cases}$$

$$f_x(x,y) = \begin{cases} 2xy^2 \cos(\frac{1}{x}) + y^2 \sin \frac{1}{x} & \text{otherwise} \\ 0 & x=0 \end{cases}$$

$$f_{yx}(x,y) = \begin{cases} 2xy \cos(\frac{1}{x}) + 2y \sin(\frac{1}{x}) & , x \neq 0 \\ 0 & x=0 \end{cases} \quad \text{--- ①}$$

$$f_y(x,y) = \begin{cases} 2yx^2 \cos \frac{1}{x} & x \neq 0 \\ 0 & x=0 \end{cases}$$

$$f_{xy}(x,y) = \begin{cases} 2yx^2 \cos \frac{1}{x} + 2yx^2 \left(-\frac{1}{x^2}\right) \left(-\sin \frac{1}{x}\right) & x \neq 0 \\ 0 & x=0 \end{cases}$$

$$f_{xy}(x,y) = \begin{cases} 4xy \cos \frac{1}{x} + 2y \sin \frac{1}{x} & x \neq 0 \\ 0 & x=0 \end{cases} \quad \text{--- ②}$$

from ① & ②

$$\boxed{f_{xy}(x,y) = f_{yx}(x,y)} \quad \forall (x,y)$$

① when $x=0$, $y \neq 0$

$$f_{xy}(x,y) = \lim_{x \rightarrow 0} (4xy \cos \frac{1}{x} + 2y \sin \frac{1}{x})$$

$$= \lim_{x \rightarrow 0} (2y \sin \frac{1}{x})$$

Since $y \neq 0$, $\Rightarrow 2y \sin \frac{1}{x}$ does not exist as $x \rightarrow 0$

$f_{xy}(x,y)$ not continuous at $x=0$, & $y \neq 0$

Similarly $f_{yx}(x,y)$ not continuous at $x=0$, $y \neq 0$

(ii) $f_{xy}(x,y) = \lim_{(x,y) \rightarrow (0,0)} 4xy \cos \frac{1}{x} + 2y \sin \frac{1}{x}$

consider

~~$f_{xy}(h,k) - f_{xy}(0,0) = 4hk \cos(\frac{1}{h}) + 2k \sin(\frac{1}{h}) - 0$~~
 ~~$f_{xy}(h,k) - f_{xy}(0,0) =$~~

$|f_{xy}(x,y) - f_{xy}(0,0)| = |4xy \cos \frac{1}{x} + 2y \sin \frac{1}{x}|$

put $x = r \cos \theta$

$y = r \sin \theta$

$= |4r^2 \cos \theta \sin \theta \cos \frac{1}{r \cos \theta} + 2r \sin \theta \sin \frac{1}{r \cos \theta}|$

$= r |4 \cos \theta \sin \theta \cos \frac{1}{r \cos \theta} + 2 \sin \theta \sin \frac{1}{r \cos \theta}|$

$\leq r |4r + 2| < \epsilon$

when $4r^2 + 2r < \epsilon$

~~$4r^2 + 2r$~~

solving this let say we get $r = \alpha$.

$\epsilon > \alpha$

$f_{xy}(x,y) = \lim_{(x,y) \rightarrow (0,0)} xy \cos \frac{1}{x} + 2y \sin \frac{1}{x}$

$= 0$ as both $x, y \rightarrow (0,0)$

and $f_{xy}(0,0) = 0$

$\therefore f_{xy}$ is continuous at origin
 similarly f_{yx} is continuous at origin

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3(b) Using Residue theorem, Show that $\int_0^\pi \frac{\cos 2\theta}{1-2a\cos\theta+a^2} d\theta = \frac{\pi a^2}{1-a^2} (a^2 < 1)$

$$I = \int_0^\pi \frac{\cos 2\theta}{1-2a\cos\theta+a^2} d\theta \quad (15)$$

$$= \frac{1}{2} \int_0^{2\pi} \frac{\cos 2\theta}{1-2a\cos\theta+a^2} d\theta \quad \text{put } z = e^{i\theta}$$

$$\Rightarrow \cos\theta = \frac{z^2+1}{2z}$$

$$\cos 2\theta = \frac{z^4+1}{2z^2}$$

$$= \frac{1}{2} \int_C \frac{z^4+1}{2z^2(i z) \left(1 - 2a \frac{z^2+1}{2z} + a^2\right)} dz$$

$$= \frac{1}{4i} \int_C \frac{(z^4+1) z dz}{z^3 (z - az^2 - a + a^2 z)}$$

$$= \frac{1}{4i} \int_C \frac{z(z^4+1) dz}{z^3 (-az^2 + (1+a^2)z - a)}$$

$$= \frac{1}{4i} \int_C \frac{1}{z^2} \frac{z^4+1}{(az^2 - a^2z - z + a)} dz$$

$$= \frac{1}{-4i} \int_C \frac{(z^4+1) dz}{z^2 (az-1)(z-a)}$$

given $a^2 < 1$
 $\Rightarrow |a| < 1$

$$= -\frac{1}{4ia} \int_C \frac{(1+z^4) dz}{z^2 \left(z - \frac{1}{a}\right) (z-a)} \Rightarrow \frac{1}{|a|} > 1$$

$\therefore z=0, z=a$ lies in C

$$f(z) = \frac{1+z^4}{z^2 \left(z - \frac{1}{a}\right) (z-a)}$$

residue at $z=0$

$$a_1 = \lim_{z \rightarrow 0} \frac{d}{dz} \frac{(1+z^4)}{\left(z - \frac{1}{a}\right) (z-a)}$$

$$= \lim_{z \rightarrow 0} \frac{\left(z - \frac{1}{a}\right) (z-a) (4z^3) - (1+z^4) \left(z-a + z - \frac{1}{a}\right)}{\left(z - \frac{1}{a}\right)^2 (z-a)^2}$$

$$= \frac{1 \times 4 \times 0 - (1) \left(-a - \frac{1}{a}\right)}{\frac{1}{a^2} \times a^2} = a + \frac{1}{a} = \frac{a^2+1}{a}$$

Residue at $z=a$

$$a_2 = \lim_{z \rightarrow a} \frac{1+z^4}{z^2(z-\frac{1}{a})}$$

$$= \lim_{z \rightarrow a} \frac{1+a^4}{a^2(a-\frac{1}{a})} = \frac{(1+a^4)}{a(a^2-1)}$$

$$I = \frac{1}{4\pi a} \int_{-\pi}^{\pi} \frac{(1+z^4) dz}{z^2(z-a)(z-\frac{1}{a})} = -\frac{1}{4\pi a} \times 2\pi i \left[\frac{1+a^4}{a(a^2-1)} + \frac{a^2+1}{a} \right]$$

$$= -\frac{\pi}{2a^2} \left[\frac{1+a^4+a^4-1}{a^2-1} \right]$$

$$= \frac{\pi}{2a^2} \times \frac{2a^4}{1-a^2}$$

$$I = \frac{\pi a^2}{1-a^2}$$

$$\therefore \int_0^{\pi} \frac{\cos 2\theta}{1-2a\cos\theta+a^2} d\theta = \frac{\pi a^2}{1-a^2}$$

✓ (3)

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3(c) Solve the following L.P.P. using Big. M. method.

$$\begin{aligned} \text{Min } Z &= x_1 + x_2 \\ \text{S.T. } 2x_1 + x_2 &\geq 4 \\ x_1 + 7x_2 &\geq 7 \\ x_1, x_2 &\geq 0 \end{aligned}$$

(15)

$$\begin{aligned} \text{min } z &= x_1 + x_2 \\ \Rightarrow \text{Max } z^* &= -x_1 - x_2 \\ 2x_1 + x_2 &\geq 4 \\ x_1 + 7x_2 &\geq 7 \\ x_1, x_2 &\geq 0 \end{aligned}$$

standard form →

$$\begin{aligned} \text{max } z^* &= -x_1 - x_2 \\ \text{to } s_1 + s_2 & \\ -MA_1 - MA_2 & \end{aligned}$$

$$2x_1 + x_2 - s_1 + A_1 = 4$$

$$x_1 + 7x_2 - s_2 + A_2 = 7$$

Simplex table :-

$C_j \rightarrow$	-1	-1	0	0	-M	-M	b	θ
	x_1	x_2	s_1	s_2	A_1	A_2		
-M A_1	2	1	-1	0	1	0	4	4
-M A_2	1	(7)	0	-1	0	1	7	$7/7=1 \rightarrow$
Z_j	-3M	-8M	M	M	-M	-M		
$C_j - Z_j$	3M-1	(8M-7)	-M	-M	0	0		
-M A_1	($\frac{13}{7}$)	0	-1	$\frac{1}{7}$	1	0	3	$\frac{21}{13} \rightarrow$
-1 x_2	$\frac{1}{7}$	1	0	$-\frac{1}{7}$	0	1	4	7
Z_j	$-\frac{13M}{7}$	$-\frac{1}{7}$	M	$\frac{M}{7} + \frac{1}{7}$	-M	0	-3M-1	
$C_j - Z_j$	($\frac{13M}{7} - \frac{6}{7}$)	0	-M	$\frac{M}{7} - \frac{1}{7}$	0	0		
-1 x_1	1	0	$\frac{7}{13}$	$\frac{1}{13}$			$\frac{21}{13}$	
-1 x_2	0	1	$\frac{1}{13}$	$-\frac{2}{13}$			$\frac{10}{13}$	
Z_j	-1	-1	$\frac{6}{13}$	$\frac{1}{13}$			$-\frac{31}{13}$	
$C_j - Z_j$	0	0	$-\frac{6}{13}$	$-\frac{1}{13}$				

Optimality reached ✓

with $x_1 = \frac{21}{13}$, $x_2 = \frac{10}{13}$

$\therefore \text{Max } z^* = -\frac{31}{13}$

$\therefore \text{Min } z = \frac{31}{13}$

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4(a) Show that the sequence $\{f_n\}$, here $f_n(x) = \frac{nx}{1+n^2x^2}$ is not uniformly convergent on any interval containing zero.

(15)

$\{f_n\} \Rightarrow$

$$f_n(x) = \frac{nx}{n^2x^2+1}$$

$$f(x) = n \rightarrow \infty \frac{nx}{n^2x^2+1} = 0$$

$$\text{let } \phi(x) = |f_n(x) - f(x)| = \left| \frac{nx}{n^2x^2+1} \right|$$

$$\text{let } \phi(x) = \frac{nx}{n^2x^2+1}$$

$$\phi'(x) = \frac{(n^2x^2+1)n - nx(2n^2x)}{(n^2x^2+1)^2} = \frac{n - n^3x^2}{(n^2x^2+1)^2}$$

$$\Rightarrow \phi'(x) = 0 \text{ when } n - n^3x^2 = 0$$

$$\Rightarrow x = \frac{1}{n}$$

$$\phi''(x) = \frac{(n^2x^2+1)^2 [-2xn^3] - (n - n^3x^2)(2)(1+n^2x^2)(2n^2x)}{(n^2x^2+1)^4}$$

$$\text{at } (x = \frac{1}{n})$$

$$\phi''(x) = \frac{4(-2n^2) - 0}{(2)^4} < 0$$

$\therefore \phi(x)$ is maximum at $x = \frac{1}{n} \in \text{interval}$ as it contains zero

$$\therefore \phi_{\max}(x) = \frac{nx \cdot \frac{1}{n}}{1 + n^2 \cdot \frac{1}{n^2}} = \frac{1}{2}$$

$$\therefore |f_n(x) - f(x)| < \frac{1}{2}$$

$$\text{let } M_n = \frac{1}{2}$$

$$\text{here } |f_n(x) - f(x)| < M$$

$$\text{but when } n \rightarrow \infty \quad \underline{M_n \neq 0}$$

\therefore From M-test

$\{f_n(x)\}$ is not uniformly convergent in any interval containing zero.

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4(b) If R is a ring, prove that $\frac{R[x]}{\langle x \rangle} \cong R$, $\langle x \rangle$ is the ideal generated by x . (15)

Consider

a mapping

$$\phi: R[x] \rightarrow R$$

$$\phi(a_0 + a_1x + a_2x^2 + \dots + a_nx^n) = a_0$$

check for homomorphism.

$$\text{let } f(x) = a_0 + a_1x + \dots + a_nx^n$$

$$g(x) = b_0 + b_1x + \dots + b_mx^m$$

$$\phi(f(x) + g(x)) = a_0 + b_0$$

$$\phi[f(x) + g(x)] = \phi(f(x)) + \phi(g(x)) \quad \text{--- (1)}$$

$$f(x) \cdot g(x) = a_0b_0 + (a_1b_0 + b_0a_1)x + \dots + a_nb_mx^{n+m}$$

$$\phi[f(x) \cdot g(x)] = a_0b_0$$

$$\phi[f(x) \cdot g(x)] = \phi[f(x)] \cdot \phi[g(x)] \quad \text{--- (2)}$$

from (1) & (2)

ϕ is homomorphism

\therefore from fundamental theorem of homomorphism

$$R \cong \frac{R[x]}{\text{kernel } \phi} \quad \text{--- (3)}$$

now, for kernel ϕ

$$\phi(a_0 + a_1x + a_2x^2 + \dots + a_nx^n) = 0$$

$$\Rightarrow a_0 = 0$$

$$\therefore a_1x + a_2x^2 + a_3x^3 + \dots + a_nx^n \in \text{kernel } \phi$$

$$\{ a_1x + a_2x^2 + \dots + a_nx^n \} = \langle x \rangle \text{ where}$$

$$(a_1, a_2, \dots, a_n) \in R$$

and $\langle x \rangle$ is ideal of R .

$$\therefore \text{kernel of } \phi = \langle x \rangle$$

\therefore from (3)

$$\frac{R[x]}{\text{kernel } \phi} \cong R$$

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4(c) Solve the following assignment problem for minimum optimal cost.

		To City					
		1	2	3	4	5	6
From City	A	12	10	15	22	18	8
	B	10	18	25	15	16	12
	C	11	10	3	8	5	9
	D	6	14	10	13	13	12
	E	8	12	11	7	13	10

Add dummy city with zero cost

(20)

12	10	15	22	18	8
10	18	25	15	16	12
11	10	3	8	5	9
6	14	10	13	13	12
8	12	11	7	13	10
0	0	0	0	0	0

Apply row operation \Rightarrow Subtracting with minimum in the row

4	2	7	14	10	0
0	8	15	5	6	2
8	7	0	5	2	0
0	8	4	7	7	6
1	5	4	0	6	3
0	0	0	0	0	0

only 5 lines require instead of 6

Apply column operation will not change anything. minimum uncovered is 2

4	0	7	14	8	0
0	6	15	5	4	2
8	5	0	5	0	6
0	6	4	7	5	6
1	3	4	0	4	3
0	0	0	0	0	0

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Again min is 2 subtraction stage

	1	2	3	4	5	6
A	6	0	7	14	8	0
B	0	4	13	3	2	0
C	10	5	0	5	0	6
D	0	4	2	5	3	4
E	2	3	4	0	4	2
F	2	0	1	1	0	1

6 lines needed

Optimal

reached

\therefore min cost = 10

$$A - 2 \Rightarrow 10$$

$$B - 6 \Rightarrow 12$$

$$C - 3 \Rightarrow 3$$

$$D - 1 \Rightarrow 6$$

$$E - 4 \Rightarrow 7$$

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min cost = 38

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Section B

5(a) Solve $(D^2 - DD' - 2D'^2)z = (2x^2 + xy - y^2)\sin xy - \cos xy$. (10)

Auxiliary equation of homogenous part

$$(D^2 - DD' - 2D'^2)z = 0$$

$$m^2 - m - 2 = 0$$

$$\Rightarrow m^2 - 2m + m - 2 = 0 \Rightarrow (m-2)m + 1(m-2) = 0$$

$$\Rightarrow (m-2)(m+1) = 0$$

$$\Rightarrow m = 2, m = -1$$

$$\therefore z_{CF} = \phi_1(y+2x) + \phi_2(y-x) \quad \text{--- (1)}$$

$$\begin{aligned} \text{Now, } z_p &= \frac{1}{(D-2D')(D+D')} [(2x^2+xy-y^2)\sin xy - \cos xy] \\ &= \frac{1}{(D-2D')(D+D')} [(2x-y)(x+y)\sin xy - \cos xy] \end{aligned}$$

$$\frac{1}{D+D'} (2x-y)(x+y)\sin xy - \cos xy \quad \begin{matrix} y-x=c \\ y=c+x \end{matrix}$$

$$= \int \frac{(x-c)(c+2x)\sin(x(c+x)) - \cos(x(c+x))}{D+D'} dx$$

$$= (x-c) \frac{\cos(cx+x^2)}{(-)} - \int [x - \cos(cx+x^2)] \frac{dx}{dx} - \int \cos(cx+x^2) dx$$

$$= (c-x)\cos(c+x)x$$

$$= (y-x-x)\cos(yx)$$

$$= (y-2x)\cos(xy)$$

$$\frac{1}{D-2D'} (y-2x)\cos(xy) \quad \begin{matrix} \text{put } y+2x=c \\ \Rightarrow y=c-2x \end{matrix}$$

$$\Rightarrow \int (c-2x-2x)\cos(x(c-2x)) dx$$

$$= \int (c-4x)\cos(cx-2x^2) dx$$

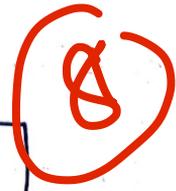
$$= \sin(cx-2x^2)$$

$$= \sin xy$$

$$\therefore \underline{z_p = \sin xy}$$

$$\therefore z = z_{CF} + z_p$$

$$z = \phi_1(y+2x) + \phi_2(y-x) + \sin xy$$



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5(b) Form a partial differential equation by eliminating the arbitrary function ϕ from $\phi(x+y+z, x^2+y^2-z^2) = 0$. What is the order of this partial differential equation? (10)

$$\text{Let } u = x+y+z \quad v = x^2+y^2-z^2 \quad p = \frac{\partial z}{\partial x}, \quad q = \frac{\partial z}{\partial y}$$

$$\therefore \phi(u, v) = 0$$

$$\Rightarrow \frac{\partial \phi}{\partial u} = 0 = \frac{\partial \phi}{\partial u} \cdot \frac{\partial u}{\partial x} + \frac{\partial \phi}{\partial v} \cdot \frac{\partial v}{\partial x} = 0$$

$$\Rightarrow \frac{\partial \phi}{\partial u} (1+p) + \frac{\partial \phi}{\partial v} (2x-2zq) = 0 \quad \text{--- (1)}$$

Again

$$\frac{\partial \phi}{\partial y} = 0$$

$$\Rightarrow \frac{\partial \phi}{\partial u} \cdot \frac{\partial u}{\partial y} + \frac{\partial \phi}{\partial v} \cdot \frac{\partial v}{\partial y} = 0$$

$$\Rightarrow \frac{\partial \phi}{\partial u} (1+q) + \frac{\partial \phi}{\partial v} (2y-2zq) = 0 \quad \text{--- (2)}$$

from (1) & (2)

$$\begin{vmatrix} 1+p & 2(x-zq) \\ 1+q & 2(y-zq) \end{vmatrix} = 0$$

$$\Rightarrow (1+p)(y-zq) - (1+q)(x-zq) = 0$$

$$\Rightarrow (1+p)(y-zq) = (1+q)(x-zq) = 0 \text{ is required partial differential equation}$$

order of P.D.E is one

✓
4

5(c) Find the value of the integral using Gauss Quadrature formula for $n=4$

$$\int_0^1 x dx$$

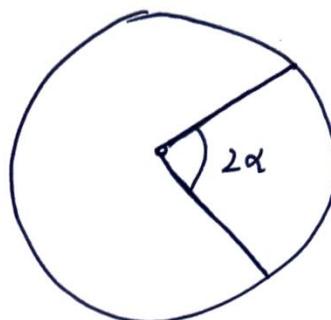
Gauss quadrature formula.

(10)

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5(d) From a uniform sphere of radius a , spherical sector of vertical angle 2α is removed. Show that the moment of inertia of the remainder of mass M about the axis of symmetry is $\frac{1}{5}Ma^2(1 + \cos \alpha)(2 - \cos \alpha)$. (10)



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5(e) If velocity distribution of an incompressible fluid at point (x, y, z) is given by $\left\{ \frac{3xz}{r^5}, \frac{3yz}{r^5}, \frac{(kz^2 - r^2)}{r^5} \right\}$, determine the parameter k such that it is a possible motion. Hence find its velocity potential. (10)

$$u = \frac{3xz}{r^5}, \quad v = \frac{3yz}{r^5}, \quad w = \frac{k(z^2 - r^2)}{r^5}$$

$$\frac{\partial u}{\partial x} = \frac{3z}{r^5} + 3xz \left(\frac{\partial}{\partial r} r^{-5} \right) = \frac{3z}{r^5} + 3xz \left(\frac{-5}{r^6} \right) \cdot \frac{x}{r}$$

$$\frac{\partial u}{\partial x} = \frac{3z}{r^5} - \frac{15x^2z}{r^7} \quad \text{--- (1)}$$

$$\frac{\partial v}{\partial y} = \frac{\partial}{\partial y} \left(\frac{3yz}{r^5} \right) = \frac{3z}{r^5} - \frac{3yz(5)}{r^6} \left(\frac{y}{r} \right)$$

$$\Rightarrow \frac{\partial v}{\partial y} = \frac{3z}{r^5} - \frac{15y^2z}{r^7} \quad \text{--- (2)}$$

$$\frac{\partial w}{\partial z} = \frac{\partial}{\partial z} \left(\frac{kz^2}{r^5} - \frac{1}{r^3} \right) = \frac{k \cdot 2z}{r^5} + \frac{kz^2 \cdot (-5) \cdot z}{r^6} \cdot \frac{z}{r}$$

$$\frac{\partial w}{\partial z} = \frac{2kz}{r^5} + \frac{3z}{r^4} \left(\frac{z}{r} \right) - \frac{5kz^3}{r^7} \quad \text{--- (3)}$$

\therefore For possible flow, continuity equation should be satisfied

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$\Rightarrow \frac{3z}{r^5} - \frac{15x^2z}{r^7} + \frac{3z}{r^5} - \frac{15y^2z}{r^7} + \frac{(2k+3)z}{r^5} - \frac{5kz^3}{r^7} = 0$$

$$\Rightarrow \frac{z}{r^5} (9+2k) - \frac{15z^3}{r^7} (x^2+y^2) - \frac{5kz^3}{r^7} = 0$$

$$\Rightarrow (9+2k)r^2 = 15(x^2+y^2) + 5kz^2$$

$$\Rightarrow 9+2k = 15 \quad \& \quad 9+2k = 5k$$

$$\Rightarrow \boxed{k=3} \quad \Rightarrow \boxed{k=3}$$

$k=3$ satisfies

\therefore For $k=3$ it is possible fluid flow

velocity potential,

$\phi,$

$$u = -\frac{\partial \phi}{\partial x} \Rightarrow \frac{\partial \phi}{\partial x} = -\frac{3xz}{r^5} \quad \text{--- (a)}$$

$$\frac{\partial \phi}{\partial y} = -\frac{3yz}{r^5} \quad \text{--- (b)}$$

$$\frac{\partial \phi}{\partial z} = \frac{r^2 - 3z^2}{r^5} \quad \text{--- (c)}$$

from (a)

$$\phi = \int \frac{-3xz}{(x^2+y^2+z^2)^{5/2}} dx$$

$$= -\frac{3z}{2} \frac{(x^2+y^2+z^2)^{-5/2+1}}{-5/2+1}$$

$$\boxed{\phi = \frac{z}{(r^2)^{3/2}} = \frac{z}{r^3}}$$

from (b) similarly

$$\boxed{\phi = \frac{z}{(r^2)^{3/2}} = \frac{z}{r^3}}$$

from (c)

$$\phi = \frac{r^2 - 3z^2}{r^5}$$

$$\text{if } \phi = \frac{z}{r^3} \Rightarrow \frac{\partial \phi}{\partial z} = \frac{r^3 - z \cdot 3r^2 \cdot \frac{z}{r}}{r^6}$$

$$= \frac{r^2 - 3z^2}{r^5} \text{ which satisfy (c)}$$

$$\therefore \text{velocity potential} = \phi = \frac{z}{r^3}$$



6(a) Write down an algorithm for Simpson's $\frac{1}{3}$ rule. Hence, compute $\int_0^1 x^2(1-x)dx$ correct up to three decimal places with step size $h = 0.1$ and compare the result with its exact value (20)

Simpson's $\frac{1}{3}$ rd rule

$$\int_{x_0}^{x_0+nh} f(x) dx = \frac{h}{3} \left[y_0 + y_n + 4(y_1 + y_3 + \dots + y_{n-1}) + 2(y_2 + y_4 + y_6 + \dots + y_{n-2}) \right]$$

Algorithm for this

- step 1: start
- step 2: read $y=f(x)$, a, b, h .
- step 3: ~~$x_0 = a, x_n = b$~~ calculate $n = \frac{b-a}{h}$
- step 4: if $n \pmod{2} \neq 0$
- step 5: ~~Print~~ stepsize(h) does not satisfy condition of $n = 2 \times$ integer and stop, else
- step 6: $x_0 = a, x_n = x_0 + nh, a[x_0] =$
- step 6: ~~$s = y_0$~~ $s = 0$
- step 7: $i = 0$ to n
 - if $i = 0$ or $i = n$
 $s = s + y(x_0 + ih)$
 - else,
if $i \pmod{2} = 0$
 $s = s + 2 \times y(x_0 + ih)$
 - else $s = s + 4 \times y(x_0 + ih)$
- step 8: next i
- step 9: $s = s \times \frac{h}{3}$
- step 10: print value of integration $\int_a^b f(x) dx = s$



$$\textcircled{a} \int_0^1 x^2(1-x) dx$$

$$= \int_0^1 (x^2 - x^3) dx = \left. \frac{x^3}{3} - \frac{x^4}{4} \right|_0^1 = \frac{1}{3} - \frac{1}{4} = \frac{1}{12} = 0.0833$$

from Simpson $\frac{1}{3}$ rd rule with $h=0.1$

x	0	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
y	0	9×10^{-3}	0.032	0.062	0.096	0.125	0.144	0.147	0.128	0.081	0

$$\begin{aligned} \therefore \int_0^1 x^2(1-x) dx &= \frac{0.1}{3} \left[0 + 0 + 4(0.009 + 0.062 + 0.125 + 0.147 + 0.081) \right. \\ &\quad \left. + 2(0.032 + 0.096 + 0.144 + 0.128) \right] \\ &= (1.693 + 0.2) \frac{1}{30} = \underline{0.0611} \end{aligned}$$

Result from Simpson $\frac{1}{3}$ rd rule = 0.0611 ✓

exact result = 0.0833

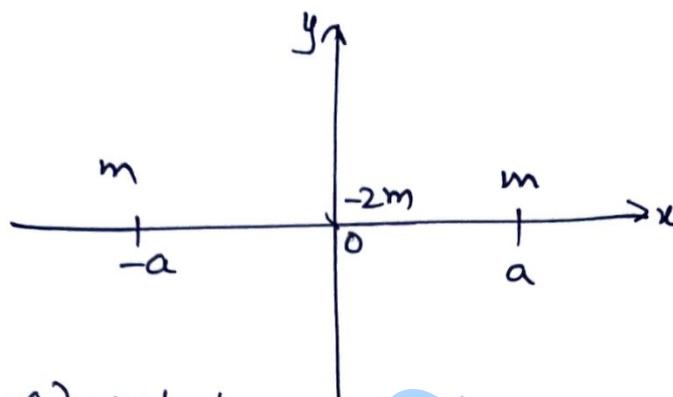
6(b) Two sources, each of strength m are placed at the points $(-a, 0), (a, 0)$ and a sink of strength $2m$ at the origin. Show that the streamlines are the curves $(x^2 + y^2)^2 = a^2(x^2 - y^2 + \lambda xy)$ where λ is a variable parameter.

Show also that the fluid speed at any point is $(2ma^2)/(r_1 r_2 r_3)$ where r_1, r_2, r_3 are the distances of the points from the sources and the sink.

(10)

Complex potential

due to all these systems



$$\Rightarrow W = -m \log(z-a) - m \log(z+a) + 2m \log z$$

$$\phi + i\psi = -m \log(x-a+iy) - m \log(x+a+iy) + 2m \log(x+iy)$$

$$\Rightarrow \phi = -m \log \sqrt{(x-a)^2 + y^2} - m \log \sqrt{(x+a)^2 + y^2} + 2m \log \sqrt{x^2 + y^2}$$

$$-m \tan^{-1}\left(\frac{y}{x-a}\right) - m \tan^{-1}\left(\frac{y}{x+a}\right) + 2m \tan^{-1}\left(\frac{y}{x}\right)$$

$$+ 2m \tan^{-1}\left(\frac{y}{x}\right)$$

$$\therefore \psi = -m \tan^{-1}\left(\frac{y}{x-a}\right) - m \tan^{-1}\left(\frac{y}{x+a}\right) + 2m \tan^{-1}\left(\frac{y}{x}\right)$$

$$= -m \tan^{-1}\left(\frac{\frac{y}{x-a} + \frac{y}{x+a}}{1 - \frac{y^2}{x^2 - a^2}}\right) + m \tan^{-1}\left(\frac{\frac{y}{x} + \frac{y}{x}}{1 - \frac{y^2}{x^2}}\right)$$

$$= -m \tan^{-1}\left(\frac{yx+ay+yx-ay}{x^2-a^2-y^2}\right) + m \tan^{-1}\left(\frac{2yx}{x^2-y^2}\right)$$

$$= -m \tan^{-1}\left(\frac{2yx}{x^2-a^2-y^2}\right) + m \tan^{-1}\left(\frac{2yx}{x^2-y^2}\right)$$

$$\frac{\phi}{m} = \tan^{-1}\left(\frac{\frac{2yx}{x^2-y^2} - \frac{2yx}{x^2-y^2-a^2}}{1 + \frac{4y^2 x^2}{(x^2-y^2)(x^2-y^2-a^2)}}\right)$$

$$\frac{\phi}{m} = \tan^{-1}\left(\frac{2yx(x^2-y^2-a^2-x^2+y^2)}{(x^2-y^2)^2 - (x^2-y^2)a^2 + 4x^2y^2}\right)$$

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$$\tan \frac{\phi}{m} = \frac{2yx(-a^2)}{(x^2+y^2)^2 - (x^2-y^2)a^2}$$

$$\Rightarrow \frac{\mu}{m} = \frac{2yx(-a^2)}{(x^2+y^2)^2 - (x^2-y^2)a^2}$$

$$\Rightarrow (x^2+y^2)^2 = (x^2-y^2)a^2 - \mu a^2(2xy)$$

Let $\mu = -\lambda$

$$\Rightarrow \boxed{(x^2+y^2)^2 = (x^2-y^2 + \lambda xy)a^2}$$
 is the streamlines

For speed

$$z = \left| \frac{\partial w}{\partial z} \right| = \left| \frac{m}{z-a} - \frac{m}{z+a} + \frac{2m}{z} \right|$$

$$= \frac{m \left(\frac{z^2-a^2}{z^2-a^2} + \frac{z^2+a^2}{z^2+a^2} - 2 \frac{z^2-a^2}{z^2-a^2} \right)}{(z-a)(z+a)z}$$

$$= \left| \frac{m \cdot 2 \cdot a^2}{r_1 r_2 r_3} \right|$$

where r_1, r_2, r_3 are distance

from ~~the~~ point z to source & sink

$$\therefore \boxed{q = \frac{2ma^2}{r_1 r_2 r_3}}$$

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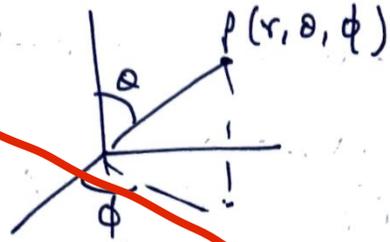
6(c) A particle is moving in a central force field given by the potential, $V = -k \frac{e^{-ar}}{r}$, where, k and a are positive constants. Construct the Hamiltonian of the particle and obtain the equation of motion. (20)

$$V = -\frac{k e^{-ar}}{r}$$

Position at P in spherical coordinates

$$r = r \cos \theta$$

$$(r \sin \theta \cos \phi, r \sin \theta \sin \phi, r \cos \theta)$$



\therefore Velocity

$$v = \dot{r} \sin \theta \cos \phi + r \sin \theta (-\sin \phi) \dot{\phi} + r \cos \theta \cos \phi \dot{\theta}$$

$$\dot{r} \sin \theta \sin \phi + r \sin \theta \cos \phi \dot{\phi} + r \cos \theta \sin \phi \dot{\theta}$$

$$\dot{r} \cos \theta + r (-\sin \theta) \dot{\theta}$$

$$v^2 = \dot{r}^2 + r^2 \dot{\phi}^2 [\sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi] + r^2 \dot{\theta}^2 [1]$$

$$+ 2r\dot{r}(\cos^2 \phi \sin \theta \cos \theta) \dot{\theta} + 2r\dot{r}(\cos \theta \sin \theta \sin^2 \phi) \dot{\phi}$$

$$+ 2r\dot{r}(\cos \theta)(-\sin \theta) \dot{\theta}$$

$$+ r^2(\dot{\theta}) \dot{\phi} + r$$

$$v^2 = \dot{r}^2 + r^2 \dot{\phi}^2 \sin^2 \theta + r^2 \dot{\theta}^2$$

Write directly this formula

$$\therefore KE = T = \frac{1}{2} m [\dot{r}^2 + r^2 \dot{\phi}^2 \sin^2 \theta + r^2 \dot{\theta}^2]$$

$$PE = V = -\frac{k e^{-ar}}{r}$$

$$v^2 = \dot{r}^2 + v \dot{\theta} + v \dot{\phi}$$

$$\therefore L = T - V = \frac{1}{2} m [\dot{r}^2 + r^2 \dot{\phi}^2 \sin^2 \theta + r^2 \dot{\theta}^2] + \frac{k e^{-ar}}{r}$$

$$p_r = \frac{\partial L}{\partial \dot{r}}$$

$$\Rightarrow p_r = m \dot{r}$$

$$p_\theta = \frac{\partial L}{\partial \dot{\theta}} = m r^2 \dot{\theta}$$

$$p_\phi = \frac{\partial L}{\partial \dot{\phi}} = m r^2 \dot{\phi} \sin^2 \theta$$

Central forces are Always Planar
 $\dot{\phi} = 0$

$$\therefore H = \cancel{Pr\dot{\theta}} + Pr\dot{\theta} + P_\theta\dot{\theta} + P_\phi\dot{\phi} - L$$

$$= mr\dot{r}^2 + mr^2\dot{\theta}^2 + mr^2\dot{\phi}^2 \sin^2\theta - \frac{1}{2}m(\dot{r}^2 + r^2\dot{\theta}^2 + r^2\dot{\phi}^2 \sin^2\theta)$$

$$H = \frac{1}{2}m(\dot{r}^2 + r^2\dot{\theta}^2 + r^2\dot{\phi}^2 \sin^2\theta) - \frac{ke^{-ar}}{r}$$

ϕ + No need

~~We know~~ $\frac{\partial H}{\partial p} = \dot{q}$

$$\dot{r} = \frac{P_r}{m}$$

$$\dot{\phi} = \frac{P_\phi}{mr^2 \sin^2\theta}$$

$$\dot{\theta} = \frac{P_\theta}{mr^2}$$

$$\therefore H = \frac{1}{2} \left(\frac{P_r^2}{m} + \frac{P_\phi^2}{mr^2 \sin^2\theta} + \frac{P_\theta^2}{mr^2} \right) - \frac{ke^{-ar}}{r}$$

$$\therefore \frac{\partial H}{\partial P_r} = \frac{P_r}{m}, \quad \frac{\partial H}{\partial P_\theta} = \frac{P_\theta}{mr^2}, \quad \frac{\partial H}{\partial P_\phi} = \frac{P_\phi}{mr^2 \sin^2\theta}$$

~~$r = \frac{P_r}{m}$~~

$$\frac{\partial H}{\partial r} = \frac{\partial}{\partial r} \left(\frac{-ke^{-ar}}{r} \right) = \frac{-ke^{-ar}}{-ar} + \frac{-ke^{-ar}}{-r^2}$$

$$-\dot{P}_r = \frac{ke^{-ar}}{ar} + \frac{ke^{-ar}}{r^2}$$

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$$\frac{\partial H}{\partial \theta} = \frac{\partial}{\partial \theta} \left(\frac{P_\phi^2}{mr^2 \sin^2\theta} \right) = \frac{P_\phi^2}{mr^2} \left(\frac{-2 \cos\theta}{\sin^3\theta} \right) = \dot{P}_\theta$$

$$\frac{\partial H}{\partial \phi} = 0 = \dot{P}_\phi$$

$$\therefore -m\ddot{r} = \frac{ke^{-ar}}{r} \left[\frac{1}{a} + \frac{1}{r} \right] \Rightarrow m\ddot{r} + \frac{ke^{-ar}}{r} \left[\frac{1}{a} + \frac{1}{r} \right]$$

$$\frac{d}{dt} (mr^2 \dot{\phi} \sin^2\theta) = 0 \Rightarrow m \frac{d}{dt} (r^2 \dot{\phi} \sin^2\theta) = 0$$

$$\frac{d}{dt} (mr^2 \dot{\theta}) = \left(\frac{m^2 r^4 \dot{\phi}^2 (-2 \cos\theta) \sin^4\theta}{mr^2 \sin^3\theta} \right)$$

$$\Rightarrow \frac{d}{dt} (mr^2 \dot{\theta}^2) + 2m r^2 \sin\theta \cos\theta \dot{\phi}^2 = 0$$