



## UPSC Mathematics 2024 Solutions Paper 1

Check out UPSC Maths Previous Year Solutions from 2001 to 2024 : [Click](#)

Test Series for UPSC Mathematics 2025: [Click](#)

Question Bank Solutions: [Click](#)

Complete Course for UPSC Maths: [Click](#)

S.No	UPSC Question	Source	
1	Paper 1 Qn -1c	Question Bank -SCB02	Qn-3
2	Paper 1 Qn -1e	Question Bank -SCC06	Qn-5
3	Paper 1 Qn -2a	FULL LENGTH TEST07 QN1- SIMILAR	
4	Paper 1 Qn -2b	Question Bank -SCB13	Qn-31
5	Paper 1 Qn -3b	Question Bank -SCB04	Qn-40
6	Paper 1 Qn -5d	Question Bank -SC E06	Qn-1
7	Paper 1 Qn -6b	Question Bank -SC E02	Qn-10
8	Paper 1 Qn -7c	UPSC 2020 QN -REPEAT	
9	Paper 2 Qn -1a	Question Bank -SCG04	Qn-18
10	Paper 2 Qn -1b	Question Bank -SCH01	Qn-3
11	Paper 2 Qn -1c	Question Bank -SCB10	Qn-54
12	Paper 2 Qn -1d	Question Bank -SCH01	Qn-5
13	Paper 2 Qn -2a	Question Bank -SCB27 Qn-22, TEST2024 REAL ANALYSIS	
14	Paper 2 Qn -2b	Question Bank -SCG07	Qn-25
15	Paper 2 Qn -3b	Question Bank -SCB29	Qn-55
16	Paper 2 Qn -4b	Question Bank -SCB26	Qn-7
17	Paper 2 Qn -5e	Question Bank -SCM03	Qn-24
18	Paper 2 Qn -7c	Question Bank -SCM04	Qn-14
19	Paper 2 Qn -8c	Question Bank -SCM07	Qn-13

Join our Telegram Channel for Important Content: <https://t.me/SuccessClap>

For Query: WhatsApp 9346856874

Visit our website <https://successclap.com>

- 1a) Let  $H$  be a subspace of  $\mathbb{R}^4$  spanned by the vectors  $v_1 = (1, -2, 5, -3)$ ,  $v_2 = (2, 3, 1, -4)$ ,  $v_3 = (3, 8, -3, -5)$ . Then find a basis and dimension of  $H$ , and extend the basis of  $H$  to a basis of  $\mathbb{R}^4$ .

$$\left[ \begin{array}{cccc} 1 & -2 & 5 & -3 \\ 2 & 3 & 1 & -4 \\ 3 & 8 & -3 & -5 \end{array} \right] \xrightarrow{R_2 \rightarrow R_2 - 2R_1} \left[ \begin{array}{cccc} 1 & -2 & 5 & -3 \\ 0 & 7 & -9 & 2 \\ 3 & 8 & -3 & -5 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 - 3R_1} \left[ \begin{array}{cccc} 1 & -2 & 5 & -3 \\ 0 & 7 & -9 & 2 \\ 0 & 8 & -18 & 4 \end{array} \right]$$

$$R_3 \rightarrow R_3 - 2R_2 \left[ \begin{array}{cccc} 1 & -2 & 5 & -3 \\ 0 & 7 & -9 & 2 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Basis  $\rightarrow (1, -2, 5, -3), (0, 7, -9, 2)$   
 $\dim = 2$

Extension  $\rightarrow$  clearly  $(0, 0, 1, 0)$   
 $(0, 0, 0, 1)$

to be added to form Basis

$$\left[ \begin{array}{cccc} 1 & -2 & 5 & -3 \\ 0 & 7 & -9 & 2 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right]$$

- 1b) Let  $T: R^3 \rightarrow R^3$  be a linear operator and  $B = (v_1, v_2, v_3)$  be a basis of  $R^3$  over R. Suppose that  $Tv_1 = (1, 1, 0)$ ,  $Tv_2 = (1, 0, -1)$ ,  $Tv_3 = (2, 1, -1)$ . Find a basis for the range space and null space of  $T$ .

Range space = Span of  $\{T(v_1), T(v_2), T(v_3)\}$

$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & -1 \\ 2 & 1 & -1 \end{bmatrix} \xrightarrow{R_2 \rightarrow R_2 - R_1} \begin{bmatrix} 1 & 1 & 0 \\ 0 & -1 & -1 \\ 2 & 1 & -1 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 - 2R_1} \begin{bmatrix} 1 & 1 & 0 \\ 0 & -1 & -1 \\ 0 & -1 & -1 \end{bmatrix}$$

$$R_3 \rightarrow R_3 - R_2 \begin{bmatrix} 1 & 1 & 0 \\ 0 & -1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

Range space Basis =  $\{(1, 1, 0), (0, -1, -1)\}$   
Rank = 2

$$T(1, 0, 0) = (1, 1, 0)$$

$$T(0, 1, 0) = (1, 0, -1)$$

$$T(0, 0, 1) = (2, 1, -1)$$

$$\begin{aligned} T(x, y, z) &= T[(1, 0, 0) + (0, 1, 0) + (0, 0, 1)] \\ &= xT(1, 0, 0) + yT(0, 1, 0) + zT(0, 0, 1) \\ &= x(1, 1, 0) + y(1, 0, -1) + z(2, 1, -1) \\ &= (x+y+2z, x+z, -y-z) \end{aligned}$$

Null Space  $T(x,y,z) = 0$

$$x+y+2z=0$$

$$x+z=0$$

$$-y-z=0$$

$$\begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 0 & -1 & -1 \end{bmatrix}$$

$$R_2 \rightarrow R_2 - R_1 \begin{bmatrix} 1 & 1 & 2 \\ 0 & -1 & -1 \\ 0 & -1 & -1 \end{bmatrix}$$

$$R_3 + R_2 - R_1 \begin{bmatrix} 1 & 1 & 2 \\ 0 & -1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$R_2 \rightarrow \frac{R_2}{-1} \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x+y+2z=0$$

$$y+z=0 \rightarrow \text{Let } z=\alpha \Rightarrow y=-\alpha$$

$$x = -y - 2z = \alpha - 2\alpha = -\alpha$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -\alpha \\ -\alpha \\ \alpha \end{pmatrix} = \alpha \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}$$

$$\text{Null Space} = (-1, -1, 1)$$

$$\text{Nullity} = 1$$

$$\text{Rank} + \text{Nullity} = 2 + 1 = 3 \leftarrow \mathbb{R}^3 \text{ (Proved)}$$

1c) Discuss the continuity of the function

$$f(x) = \begin{cases} \frac{1}{1 - e^{-1/x}}, & x \neq 0 \\ 0, & x = 0 \end{cases}$$

for all values of  $x$ .

### Question Bank: SC-B02-On-3

RHL:  $\lim_{h \rightarrow 0^+} f(0+h) = \lim_{h \rightarrow 0^+} \frac{1}{1 - e^{-1/h}}$

$$\lim_{h \rightarrow 0^+} e^{-1/h} = \frac{1}{e^{1/h}} = \frac{1}{e^\infty} = \frac{1}{\infty} = 0$$

$$\lim_{h \rightarrow 0^+} \frac{1}{1 - e^{-1/h}} = \frac{1}{1 - 0} = 1$$

LHL:  $\lim_{h \rightarrow 0^-} f(0-h) = \lim_{h \rightarrow 0^-} \frac{1}{1 - e^{1/h}}$

$$\lim_{h \rightarrow 0^-} e^{1/h} \rightarrow e^{\infty} \rightarrow \infty$$

$$\lim_{h \rightarrow 0^-} \frac{1}{1 - e^{1/h}} \rightarrow \frac{1}{\infty} \rightarrow 0$$

$\lim_{h \rightarrow 0^+} f(0+h) \neq \lim_{h \rightarrow 0^-} f(0-h)$  So Discontinuous at  $x=0$   
For  $x \neq 0$  continuous

- 1d) Expand  $\ln(x)$  in powers of  $(x - 1)$  by Taylor's theorem and hence find the value of  $\ln(1.1)$  correct up to four decimal places.

Taylor:

$$f(x) = f(a) + (x-a)f'(a) + \frac{(x-a)^2}{2!}f''(a) + \frac{(x-a)^3}{3!}f'''(a) + \frac{(x-a)^4}{4!}f^{(iv)}(a) + \dots$$

$$f(x) = \ln x \quad a = 1$$

$$f(1) = \ln 1 = 0$$

$$f'(x) = \frac{1}{x} \quad f'(1) = 1$$

$$f''(x) = -\frac{1}{x^2} \quad f''(1) = -1$$

$$f'''(x) = \frac{2}{x^3} \quad f'''(1) = 2$$

$$f^{(iv)}(x) = -\frac{6}{x^4} \quad f^{(iv)}(1) = -6$$

$$f(x) = (x-1) - \frac{(x-1)^2}{2!} + \frac{(x-1)^3}{3!} - \frac{(x-1)^4}{4!} + \dots$$

$$\frac{2}{3!} = \frac{1}{3} \quad \frac{6}{4!} = \frac{1}{4}$$

$$f(x) = (x-1) - \frac{(x-1)^2}{2} + \frac{(x-1)^3}{3} - \frac{(x-1)^4}{4} + \dots$$

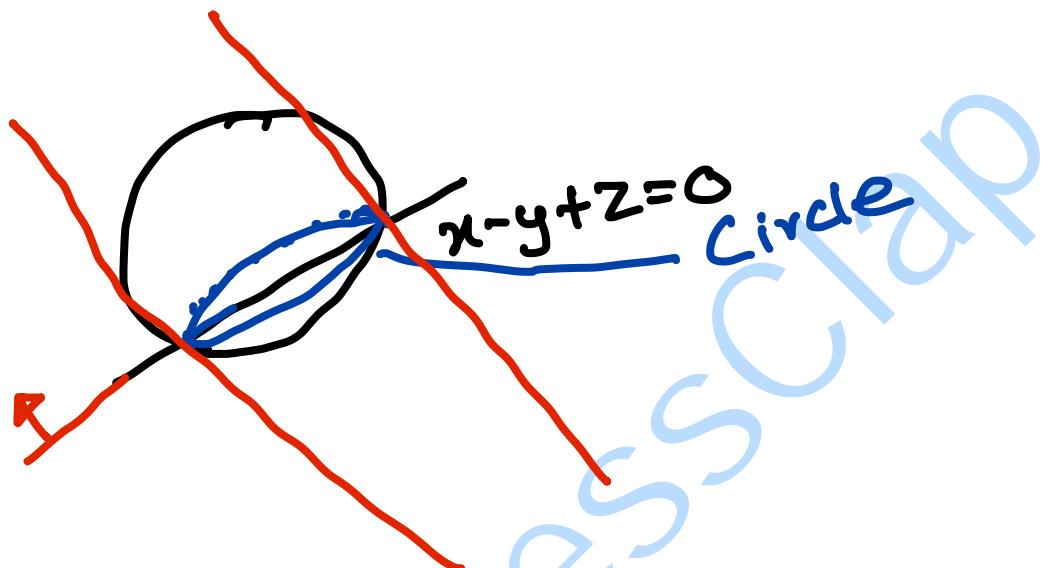
$$x = 1.1 \quad x-1 = 0.1$$

$$\begin{aligned} \ln(1.1) &= 0.1 - \frac{(0.1)^2}{2} + \frac{(0.1)^3}{3} - \frac{(0.1)^4}{4} + \dots \\ &= 0.1 - 0.005 + 0.00033 - 0.000025 \\ &= 0.095305 \end{aligned}$$

- 1e) Find the equation of the right circular cylinder which passes through the circle  $x^2 + y^2 + z^2 = 9$ ,  $x - y + z = 3$ .

## Question Bank SC-C06 Qn-5

Guiding Circle  $\rightarrow \left. \begin{array}{l} x^2 + y^2 + z^2 = 9 \\ x - y + z = 3 \end{array} \right\}$



Axis of Cylinder  $\Rightarrow$  perpendicular to plane

$\uparrow$  DR  $(a, b, c)$   $\Rightarrow$  DR is  $(1, -1, 1)$   
 $\frac{ax+by+cz}{d} = 0$  why  $1 \cdot x - 1 \cdot y + 1 \cdot z = 0$  (plane)

$P(x_1, y_1, z_1)$   
 $Q$  Eqn of Generator thru P is  
 $\frac{x-x_1}{1} = \frac{y-y_1}{-1} = \frac{z-z_1}{1} = \gamma$

Another pt Q on generator is  
 $(x_1 + \gamma, -\gamma + 4_1, \gamma + z_1)$

Generators pass thru circle  $\begin{cases} x^2 + y^2 + z^2 = 9 \\ x - y + z = 3 \end{cases}$

↳ Let Q is on circle

$$\begin{cases} (x_1 + \gamma)^2 + (-\gamma + 4_1)^2 + (\gamma + z_1)^2 = 9 & \text{--- (1)} \\ (x_1 + \gamma) - (-\gamma + 4_1) + (\gamma + z_1) = 3 & \text{--- (2)} \end{cases}$$

$$(1) \Rightarrow 3\gamma^2 + 2\gamma(x_1 + 4_1 + z_1) + x_1^2 + 4_1^2 + z_1^2 - 9 = 0 \quad \text{--- (4)}$$

$$(2) \Rightarrow \gamma = \frac{1}{3}(3 - x_1 - 4_1 - z_1) \quad \text{--- (5)}$$

Eliminate  $\gamma$  by putting  $\gamma$  from Eqn 5

in Eq 4

$$\frac{1}{3}(3 - x_1 - 4_1 - z_1)^2 + \frac{2}{3}(3 - x_1 - 4_1 - z_1)(x_1 + 4_1 + z_1) + x_1^2 + 4_1^2 + z_1^2 - 9 = 0$$

$$\Rightarrow x_1^2 + 4_1^2 + z_1^2 + 4_1 z_1 - z_1 x_1 + x_1 4_1 = 9$$

$$\text{Locus P is } x^2 + y^2 + z^2 + 4z - 2x + xy = 9$$

- 2a) Consider a linear operator  $T$  on  $\mathbb{R}^3$  over  $\mathbb{R}$  defined by  $T(x,y,z) = (2x, 4x-y, 2x+3y-z)$  is  $T$  invertible? If yes, justify your answer and find  $T^{-1}$ .

**Similar Qn: Full Length Test-07, 2024, Qn1**

Method 1:

To show invertible  $\Rightarrow$  let  $T(x,y,z) = 0$   
then show  $x=0, y=0, z=0$

$$T(x,y,z) = 0 \Rightarrow 2x=0 \Rightarrow x=0$$

$$4x-y=0 \Rightarrow y=0 \text{ as } x=0$$

$$2x+3y-z=0 \Rightarrow z=0 \text{ as } x=y=0$$

$$T(x,y,z) = (P, Q, R)$$

$$\Rightarrow 2x, 4x-y, 2x+3y-z = P, Q, R$$

$$\Rightarrow 2x=P \Rightarrow x=\frac{P}{2}$$

$$4x-y=Q \Rightarrow y=4x-Q=2P-Q$$

$$2x+3y-R \Rightarrow z=2x+3y-R$$

$$= P + 6P - 3Q - R$$

$$= 7P - 3Q - R$$

$$T^{-1}(P, Q, R) = (x, y, z)$$

$$= \left( \frac{P}{2}, 2P-Q, 7P-3Q-R \right)$$

$$T^{-1}(p, q, r) = \left( \frac{p}{2}, 2p-q, 7p-3q-r \right)$$

### Method 2

$$T(x, y, z) = (2x, 4x-y, 2x+3y-z)$$

$$T(1, 0, 0) = (2, 4, 2) = 2(1, 0, 0) + 4\begin{pmatrix} 0, 0, 1 \\ 0, 0, 1 \end{pmatrix}$$

$$T(0, 1, 0) = (0, -1, 3) = 0(1, 0, 0) - 1(0, 0, 1) + 3\begin{pmatrix} 0, 0, 1 \end{pmatrix}$$

$$T(0, 0, 1) = (0, 0, -1) = 0(1, 0, 0) + 0(0, 0, 1) - 1(0, 0, 1)$$

$$[T]_B = A = \begin{bmatrix} 2 & 0 & 0 \\ 4 & -1 & 0 \\ 2 & 3 & -1 \end{bmatrix}$$

$$|A| = 2(-1) = 2 \neq 0$$

$\Rightarrow A$  is invertible  
 $\Rightarrow T$  is invertible

$$A^{-1} = \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 2 & -1 & 0 \\ 7 & -3 & -1 \end{bmatrix}$$

$$A^{-1}\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \frac{x}{2}, 2x-y, 7x-3y-z$$

$$T^{-1}(x, y, z) = \left( \frac{x}{2}, 2x-y, 7x-3y-z \right)$$

- 2b) If  $u = (x+y)/(1-xy)$  and  $v = \tan^{-1}x + \tan^{-1}y$ , then find  $\partial(u, v)/\partial(x, y)$ . Are  $u$  and  $v$  functionally related? If yes, find the relationship.

### Question Bank SCB/3 Qn31

$$u = \frac{x+y}{1-xy} \quad \frac{\partial u}{\partial x} = \frac{1+y^2}{(1-xy)^2} \quad \frac{\partial u}{\partial y} = \frac{1+x^2}{(1-xy)^2}$$

$$v = \tan^{-1}x + \tan^{-1}y$$

$$\frac{\partial v}{\partial x} = \frac{1}{1+x^2} \quad \frac{\partial v}{\partial y} = \frac{1}{1+y^2}$$

$$J = \frac{\partial(u, v)}{\partial(x, y)} = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix} = \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} - \frac{\partial u}{\partial y} \cdot \frac{\partial v}{\partial x}$$

$$= \frac{1+y^2}{(1-xy)^2} \cdot \frac{1}{1+y^2} - \frac{1+x^2}{(1-xy)^2} \cdot \frac{1}{1+x^2}$$

$$= 0$$

$J=0 \Rightarrow$  They are not independent

$$v = \tan^{-1}x + \tan^{-1}y = \tan^{-1} \frac{x+y}{1-xy} = \tan^{-1}u$$

$$\underline{u = \tan v} \quad \text{relation b/w } u \& v$$

- 2c) Find the image of the line  $x = 3 - 6t$ ,  $y = 2t$ ,  $z = 3 + 2t$  in the plane  $3x + 4y - 5z + 26 = 0$ .

Line eqn is  $\frac{x-3}{-6} = \frac{y-0}{2} = \frac{z-3}{2} = t$

↪ clearly  $A(3,0,3)$  lie on line

→ Find image of A on plane  $(A')$

→ Find point where line cuts plane ie pt B

Our required line  
is  $A'B$

To find  $A'$ :

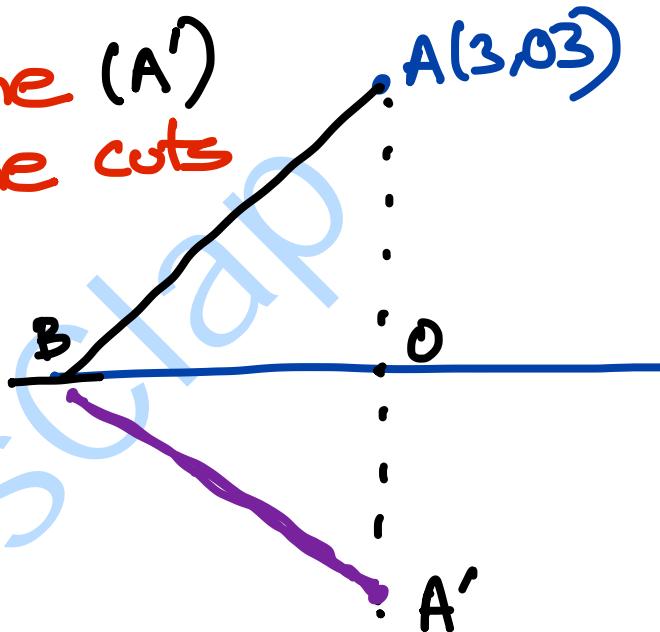
Line perpendicular to plane  
has DRS  $(3, 4, -5)$  and also pass  
thru  $(3, 0, 3)$

$$\text{Line is } \frac{x-3}{3} = \frac{y-0}{4} = \frac{z-3}{-5} = k$$

Line meets plane at O

Find O: Any pt on line is  
 $(3k+3, 4k, -5k+3)$

$$\begin{aligned} \text{pt lie on plane } & 3x + 4y - 5z + 26 = 0 \\ & 3(3k+3) + 4(4k) - 5(-5k+3) + 26 = 0 \\ & 9k+9+16k+25k-15+26=0 \end{aligned}$$



$$50k = -20 \quad k = -\frac{2}{5}$$

$$O \text{ is } \left( \frac{-6}{5} + 3, \frac{-8}{5}, 5 \right) \quad \frac{-6+15}{5} =$$

$$\left( \frac{9}{5}, \frac{-8}{5}, 5 \right)$$

$O$  is mid pt of  $A$  &  $A'$   
 If  $A'$  is  $(\alpha, \beta, \gamma)$   $\left(O = \frac{A+A'}{2}\right)$

$$\frac{9}{5} = \frac{3+\alpha}{2} \quad \frac{-8}{5} = \frac{0+\beta}{2} \quad 5 = \frac{3+\gamma}{2}$$

$$\alpha = \frac{18}{5} - 3 = \frac{3}{5} \quad \beta = -\frac{16}{5} \quad \gamma = 7$$

$$\left( \frac{3}{5}, -\frac{16}{5}, 7 \right)$$

Find pt B:  $\frac{x-3}{-6} = \frac{y}{2} = \frac{z-3}{2} = t$

Any pt is  $(-6t+3, 2t, 2t+3)$

B - lie on plane  $3x+4y-5z+26=0$

$$3(-6t+3) + 4(2t) - 5(2t+3) + 26 = 0$$

$$\Rightarrow t=1$$

pt B is  $(-3, 2, 5)$

$A'$  is  $\left(\frac{3}{5}, -\frac{16}{5}, 7\right)$

$B$  is  $(-3, 2, 5)$

DRs of  $A'B$  is  $\frac{3}{5} + 3, -\frac{16}{5} - 2, 7 - 5$

$$\left(\frac{18}{5}, -\frac{26}{5}, 2\right)$$

$$\sim (18, -26, 10)$$

$$\sim (9, -13, 5)$$

$A'B$  lie eqn is

$$\frac{x - \frac{3}{5}}{9} = \frac{y + \frac{16}{5}}{-13}, \frac{z - 5}{7}$$

- 3a) Let  $V = M_{2 \times 2}(R)$  denote a vector space over the field of real numbers. Find the matrix of the linear mapping  $\phi: V \rightarrow V$  given by  $\phi(v) = \begin{pmatrix} 1 & 2 \\ 3 & -1 \end{pmatrix}v$  with respect to standard basis of  $M_{2 \times 2}(\mathbb{R})$ , and hence find the rank of  $\phi$ . Is  $\phi$  invertible? Justify your answer.

**Standard Basis**

$$b_1 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, b_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, b_3 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, b_4 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$v = \begin{pmatrix} x & y \\ z & t \end{pmatrix} \quad \phi(v) = \begin{pmatrix} 1 & 2 \\ 3 & -1 \end{pmatrix} \begin{pmatrix} x & y \\ z & t \end{pmatrix} =$$

$$= \begin{bmatrix} x+2z & y+2t \\ 3x-z & 3y-t \end{bmatrix} \checkmark$$

$$\phi(b_1) = \begin{pmatrix} 1 & 0 \\ 3 & 0 \end{pmatrix} = 1b_1 + 0b_2 + 3b_3 + 0b_4$$

$$\phi(b_2) = \begin{pmatrix} 0 & 1 \\ 0 & 3 \end{pmatrix} = 0b_1 + 1b_2 + 0b_3 + 3b_4$$

$$\phi(b_3) = \begin{pmatrix} 2 & 0 \\ -1 & 0 \end{pmatrix} = 2b_1 + 0b_2 - b_3 + 0b_4$$

$$\phi(b_4) = \begin{pmatrix} 0 & 2 \\ 0 & -1 \end{pmatrix} = 0b_1 + 2b_2 + 0b_3 - b_4$$

Matrix is

$$\begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 0 & 2 \\ 3 & 0 & -1 & 0 \\ 0 & 3 & 0 & -1 \end{bmatrix}$$

Transpose  
values

## Rank : Transposing

$$\left[ \begin{array}{cccc} 1 & 0 & 3 & 0 \\ 0 & 1 & 0 & 3 \\ 2 & 0 & -1 & 0 \\ 0 & 2 & 0 & -1 \end{array} \right] \quad \begin{array}{l} R_3 \rightarrow R_3 - 2R_1 \\ R_4 \rightarrow R_4 - 2R_2 \end{array}$$

$$\left[ \begin{array}{cccc} 1 & 0 & 3 & 0 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{array} \right] \quad \text{Rank} = 4$$

## Invertible:

Method 1: we got rank = 4

$$\begin{aligned} \text{rank} + \text{nullity} &= 4 \\ \Rightarrow \text{nullity} &= 0 \quad \text{as rank} = 4 \end{aligned}$$

$\Rightarrow$  Invertible

$$\text{Method 2}: \quad \varphi(v) = \begin{pmatrix} x+2z & y+2t \\ 3x-z & 3y-t \end{pmatrix}$$

$$v = \begin{pmatrix} x & y \\ z & t \end{pmatrix} \quad \text{Now } \varphi(v) = 0 \Rightarrow \begin{array}{l} x+2z=0 \\ y+2t=0 \\ 3x-z=0 \\ 3y-t=0 \end{array}$$

$\Rightarrow x=y=z=t=0 \Rightarrow v=0 \text{ matrix}$   
so Invertible

- 3b) Find the volume of the greatest cylinder which can be inscribed in a cone of height  $h$  and semi-vertical angle  $\alpha$ .

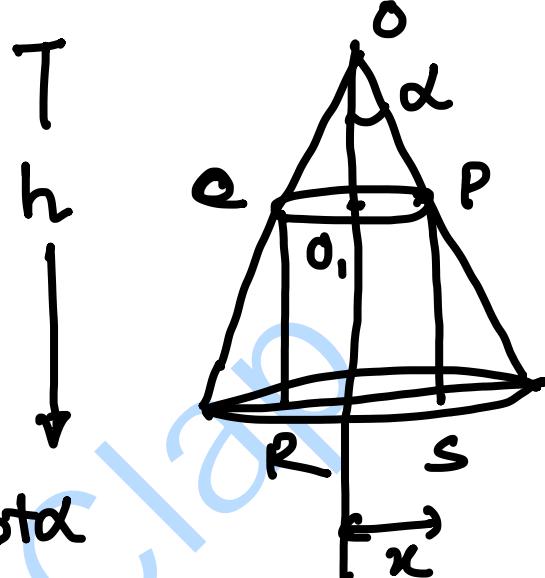
### Question Bank : SCB04 On 40

PQRS Cylinder

Cone height =  $h$

Cylinder radius =  $x$   
 $= O_1 P$

Cylinder height =  
 $h - OO_1 = h - x \cot \alpha$



$$\begin{aligned} \text{Volume } V &= \pi x^2 h = \\ &= \pi x^2 (h - x \cot \alpha) \\ &= \pi [hx^2 - x^3 \cot \alpha] \end{aligned}$$

$$\begin{aligned} \tan \alpha &= \frac{x}{OO_1}, \\ OO_1 &= x \cot \alpha \end{aligned}$$

$$\begin{aligned} \frac{dV}{dx} &= 0 \Rightarrow \pi [2hx - 3x^2 \cot \alpha] = 0 \\ &\Rightarrow \pi x [2h - 3x \cot \alpha] = 0 \Rightarrow \\ &\Rightarrow x = 0 \text{ or } x = \frac{2h}{3} \tan \alpha \end{aligned}$$

$$\begin{aligned} \frac{d^2V}{dx^2} &= \pi [2h - 6x \cot \alpha] \Big|_{x=\frac{2h}{3} \tan \alpha} = \\ &= \pi \left[ 2h - \frac{6 \cdot 2h}{3} \tan \alpha \cdot \cot \alpha \right] = -2\pi h = \text{Negative} \\ &\Rightarrow \text{Max} \end{aligned}$$

$$\begin{aligned} x &= \frac{2h}{3} \tan \alpha & V &= \pi [hx^2 - x^3 \cot \alpha] \\ & & &= \frac{4}{27} \pi h^3 \tan^2 \alpha \end{aligned}$$

- 3c) Find the vertex of the cone  $4x^2 - y^2 + 2z^2 + 2xy - 3yz + 12x - 11y + 6z + 4 = 0$ .

Make it Homogeneous

$$F(x, y, z, t) = 4x^2 - y^2 + 2z^2 + 2xy - 3yz + 12x - 11y + 6z + 4t^2$$

$$\frac{\partial F}{\partial x} = 8x + 2y + 12t = 0 \quad t=1 \Rightarrow 8x + 2y + 12 = 0 \quad \text{Eq, 1}$$

$$\frac{\partial F}{\partial y} = -2y + 2x - 3z - 11t = 0 \quad t=1 \Rightarrow 2x - 2y - 3z - 11 = 0 \quad \text{Eq, 2}$$

$$\frac{\partial F}{\partial z} = 0 = 4z - 3y + 6t \quad t=1 \Rightarrow 4z - 3y + 6 = 0 \quad \text{Eq, 3}$$

$$\frac{\partial F}{\partial t} = 0 = 12x - 11y + 6z + 8t \quad t=1 \Rightarrow 12x - 11y + 6z + 8 = 0 \quad \text{Eq, 4}$$

Use only 3 eqns (Eq 1, 2, 3) to  
solve  $x, y, z$  gives  $x=-1, y=-2, z=-3$

Put this value in Eq 4  $\Rightarrow$  satisfy Eq 4  
 $\Rightarrow$  Cone is verified

Vertex is  $(-1, -2, -3)$

- 4a) Let  $A = \begin{pmatrix} 3 & 2 & 4 \\ 2 & 0 & 2 \\ 4 & 2 & 3 \end{pmatrix}$  be a  $3 \times 3$  matrix. Find the eigenvalues and the corresponding eigenvectors of  $A$ . Hence find the eigenvalues and the corresponding eigenvectors of  $A^{-15}$ , where  $A^{-15} = (A^{-1})^{15}$ .

$$(A - \lambda I) = 0 \Rightarrow \begin{vmatrix} 3-\lambda & 2 & 4 \\ 2 & -\lambda & 2 \\ 4 & 2 & 3-\lambda \end{vmatrix} = 0 \Rightarrow$$

$$\begin{vmatrix} 3 & 2 \\ 2 & 0 \end{vmatrix} = -4 \quad \begin{vmatrix} 0 & 2 \\ 2 & 3 \end{vmatrix} = -4 \quad \begin{vmatrix} 3 & 4 \\ 4 & 3 \end{vmatrix} = -7$$

$$-4 - 4 - 7 = -15$$

$$\text{Trace}(A) = 3 + 0 + 3 = 6$$

$$|A| = 8 \quad (\text{By Calculation})$$

$$\lambda^3 - (\text{Trace})\lambda^2 + (\text{adj})\lambda - |A| = 0$$

$$\lambda^3 - 6\lambda^2 - 15\lambda - 8 = 0$$

$$\Rightarrow (\lambda - 8)(\lambda + 1)^2 = 0 \Rightarrow \lambda = 8, -1, -1$$

$$\underline{\lambda = 8} :$$

$$A - \lambda I = \begin{bmatrix} -5 & 2 & 4 \\ 2 & -8 & 2 \\ 4 & 2 & -5 \end{bmatrix} \xrightarrow{R_2 \rightarrow \frac{R_2}{2}} \begin{bmatrix} -5 & 2 & 4 \\ 1 & -4 & 1 \\ 4 & 2 & -5 \end{bmatrix}$$

$$R_1 \rightarrow R_1 + 5R_2 \quad R_3 \rightarrow R_3 - 4R_2 \quad \begin{bmatrix} 0 & -18 & 9 \\ 1 & -4 & 1 \\ 0 & 18 & -9 \end{bmatrix}$$

$$R_3 \rightarrow R_3 + R_1 \begin{bmatrix} 0 & -18 & 9 \\ 1 & -4 & 1 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1 + \frac{R_1}{9}} \begin{bmatrix} 0 & -2 & 1 \\ 1 & -4 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} \cdot \\ \cdot \\ \cdot \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{array}{l} -2y + z = 0 \\ x - 4y + z = 0 \end{array}$$

$$\text{Let } y = t \Rightarrow z = 2y = 2t$$

$$x = 4y - z = 4t - 2t = 2t$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2t \\ t \\ 2t \end{bmatrix} = t \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}$$

E-Vector:  $t=1 \Rightarrow (2, 1, 2)$

$$\underline{A = -I}$$

$$A \cdot \lambda I = \begin{bmatrix} 4 & 2 & 4 \\ 2 & 1 & 2 \\ 4 & 2 & 4 \end{bmatrix}$$

$$\begin{array}{l} R_1 \rightarrow R_1 - 2R_2 \\ R_3 \rightarrow R_3 - 2R_2 \end{array} \begin{bmatrix} 0 & 0 & 0 \\ 2 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

only eqn  $2x + y + 2z = 0$

$$\text{Let } x = \alpha, z = \beta \Rightarrow y = -2x - 2z = -2\alpha - 2\beta$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} \alpha \\ -2\alpha - 2\beta \\ \beta \end{bmatrix} = \alpha \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} + \beta \begin{bmatrix} 0 \\ -2 \\ 1 \end{bmatrix}$$

Eigen vectors are  $\begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -2 \\ 1 \end{pmatrix}$

Eigen value of  $A$  is  $(8, -1, -1)$

Eigen value of  $A^{-15}$  is  $\left(\frac{1}{8^{15}}, \frac{1}{(-1)^{15}}, \frac{1}{(-1)^{15}}\right)$

is  $\left(\frac{1}{8^{15}}, -1, -1\right)$

Eigen vectors of  $A$  are

$$\begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -2 \\ 1 \end{pmatrix}$$

✓ Eigen vectors of  $A^{-15}$  are same as  
Eigen vector of  $A$  : NOTE

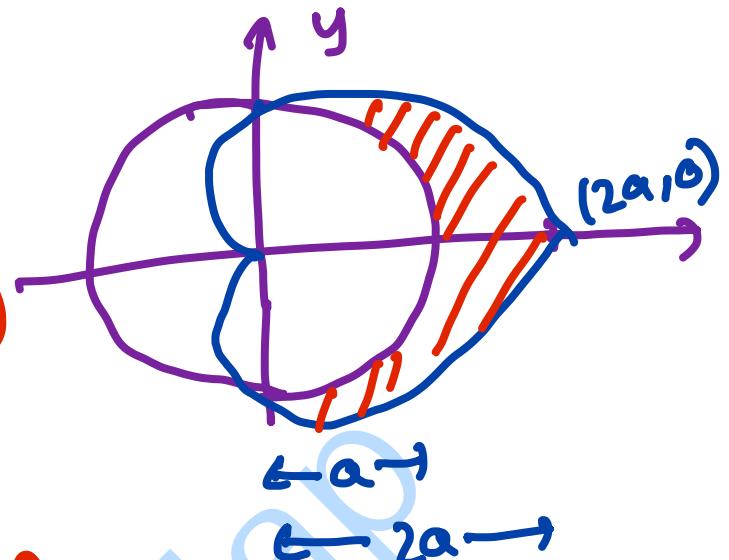
why  $AX = \lambda X$   $X$ : Eigen Vector of  $A$   
 $A^2X = \lambda AX = \lambda^2 X \Rightarrow A^3X = \lambda^3 X \Rightarrow A^9X = \lambda^9 X$   
 $\Rightarrow A^{-15}X = \lambda^{-15} X$  Imp

- 4b) Using double integration, find the area lying inside the cardioid  $r = a(1 + \cos \theta)$  and outside the circle  $r = a$ .

$$dx dy = r dr d\theta$$

$$r : r = a \text{ to } r = a(1 + \cos \theta)$$

$$\theta : \theta = -\frac{\pi}{2} \text{ to } \theta = \frac{\pi}{2}$$



$$I = \iint dx dy = \iint r dr d\theta$$

$$= \int_{-\pi/2}^{\pi/2} \int_{r=a}^{r=a(1+\cos\theta)} r dr d\theta$$

$$= \int_{-\pi/2}^{\pi/2} \left(\frac{1}{2}\right) r^2 \Big|_a^{a(1+\cos\theta)} d\theta =$$

$$= \frac{1}{2} \int_{-\pi/2}^{\pi/2} [a^2(1+\cos\theta)^2 - a^2] d\theta \quad \left[ \begin{array}{l} \int_a^a = 0 \\ \int_0^a = a \end{array} \right]$$

$$= 2 \times \frac{a^2}{2} \int_0^{\pi/2} [2\cos^2\theta + 2\cos\theta] d\theta$$

$$= a^2 \left[ \frac{1}{2} \times \frac{\pi}{2} + 2 \cdot \frac{1}{2} \right] = \frac{a^2(\pi+8)}{4}$$

$$\left[ \int_0^{\pi/2} \cos^n \theta d\theta = \left[ \frac{n-1}{n} \frac{n-3}{n-2} \dots \right] \right] \quad \begin{array}{l} \pi/2 \text{ Even} \\ 1, \text{ odd} \end{array}$$

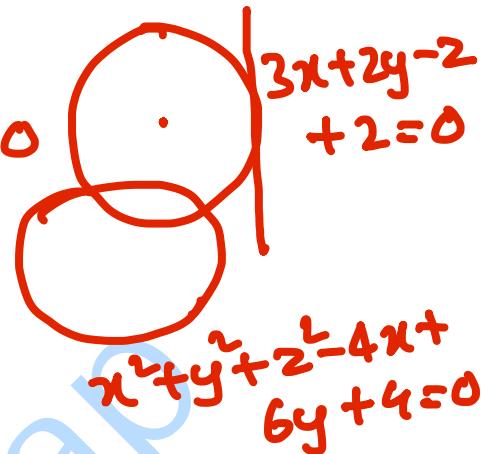
- 4c) Find the equation of the sphere which touches the plane  $3x + 2y - z + 2 = 0$  at the point  $(1, -2, 1)$  and cuts orthogonally the sphere  $x^2 + y^2 + z^2 - 4x + 6y + 4 = 0$ .

Let given sphere

$$x^2 + y^2 + z^2 + 2gx + 2fy + 2hz + c = 0$$

Tangent plane at  $(1, -2, 1)$

$$x - 2y + z + g(x+1) + f(y-2) + h(z+1) + c = 0$$



$$\left[ \begin{array}{l} (g+1)x + (f-2)y + (h+1)z + (g-2f+h+c) = 0 \\ \text{But given tangent is } 3x + 2y - z + 2 = 0 \end{array} \right]$$

$$\Rightarrow \frac{g+1}{3} = \frac{f-2}{2} = \frac{h+1}{-1} = \frac{g-2f+h+c}{2} = k$$

$$\Rightarrow g = 3k-1, f = 2k+2, h = -k-1, \\ g-2f+h+c = 2k$$

Since sphere cuts orthogonally  $x^2 + y^2 + z^2 - 4x + 6y + 4 = 0$

$$2g(-2) + 2f(3) + 2h(0) = c+4 \\ -4g + 6f = c+4$$

$$\text{Put } g = 3k-1, f = 2k+2, h = -k-1 \\ \text{in } g-2f+h+c = 2k$$

$$(3k-1) - 2(2k+2) + (-k-1) + c = 2k$$

$$\underline{-4k + c = 6}$$

→ Put  $g, f, h$  in  $-4g+6f=c+4$

$$\begin{array}{r} -12k+4+12k+12=c+4 \\ \times \quad \quad \quad \times \end{array}$$

$$c=12$$

$$\rightarrow c=12 \Rightarrow -4k+c=6 \Rightarrow 4k=c-6=6 \Rightarrow k=\frac{3}{2}$$

$$k=\frac{3}{2} \Rightarrow g=3k-1=\frac{7}{2}$$

$$f=2k+2=5$$

$$h=-k-1=-\frac{5}{2}$$

Required sphere is

$$x^2+y^2+z^2+7x+10y-5z+12=0$$

- 5a) Find the orthogonal trajectories of the family of curves  $r = c(\sec \theta + \tan \theta)$ , where  $c$  is a parameter.

$$v = c(\sec \theta + \tan \theta)$$

$$\frac{dv}{d\theta} = c[\sec \theta \tan \theta + \sec^2 \theta]$$

$$= c \sec \theta [\tan \theta + \sec \theta]$$

$$= r \sec \theta$$

$$\downarrow \text{orthogonal} \quad \frac{dv}{d\theta} \neq -r \frac{d\theta}{dr}$$

$$-r \frac{d\theta}{dr} = r \sec \theta$$

$$\sec \theta = \frac{1}{c \cos \theta}$$

$$-\cos \theta d\theta = \frac{1}{r} dr$$

, Integrating

$$-\sin \theta = \ln r + C$$

$$C - \sin \theta = \ln r$$

$$r = e^{\frac{C}{r}} \cdot e^{-\sin \theta}$$

$$= K e^{-\sin \theta}$$

- 5b) Solve the integral equation  $y(t) = \cos t + \int_0^t y(x)\cos(t-x)dx$  using Laplace transform.

$$y(t) = \cos t + \int_0^t y(u)\cos(t-u)du$$

Taking Laplace

$$\mathcal{L}(y(t)) = \frac{p}{p^2+1} + \mathcal{L}\{y(t)\} \cdot \mathcal{L}(\cos t)$$

$$= \frac{p}{p^2+1} + \mathcal{L}(y(t)) \left( \frac{p}{p^2+1} \right)$$

$$\mathcal{L}(y(t)) \left[ 1 - \frac{p}{p^2+1} \right] = \mathcal{L}(y(t)) \left[ \frac{p^2-p+1}{p^2+1} \right] = \frac{p}{p^2+p+1}$$

$$\mathcal{L}(y(t)) = \frac{p}{p^2-p+1} = \frac{p}{\left(p-\frac{1}{2}\right)^2 + \frac{3}{4}} u$$

$$y(t) = \mathcal{L}^{-1}\left\{ \frac{p}{p^2+\left(\frac{\sqrt{3}}{2}\right)^2} \right\} = e^{t/2} \mathcal{L}^{-1}\left\{ \frac{p}{p^2+\left(\frac{\sqrt{3}}{2}\right)^2} \right\}$$

$$= e^{t/2} \cos \frac{\sqrt{3}}{2} t$$

- 5c) At any time  $t$  (in seconds), the coterminous edges of a variable parallelepiped are represented by the vectors

$$\begin{aligned}\bar{\alpha} &= t\hat{i} + (t+1)\hat{j} + (2t+1)\hat{k} \\ \bar{\beta} &= 2t\hat{i} + (3t-1)\hat{j} + t\hat{k} \\ \bar{\gamma} &= \hat{i} + 3t\hat{j} + \hat{k}\end{aligned}$$

What is the rate of change of the vectorial area of the parallelogram, whose coterminous edges are  $\bar{\alpha}$  and  $\bar{\gamma}$ ? Also find the rate of change of the volume of the parallelepiped at  $t = 1$  second.

$$\begin{aligned}\alpha \times \gamma &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ t & t+1 & 2t+1 \\ 1 & 3t & 1 \end{vmatrix} = A \\ &= i(-6t^2 - 2t + 1) + j(t+1) + k(3t^2 - t - 1)\end{aligned}$$

$$\frac{dA}{dt} = i(-12t - 2) + j + k(6t - 1)$$

$$\left. \frac{dA}{dt} \right|_{t=1} = -14\hat{i} + \hat{j} + 5\hat{k}$$

$$\begin{aligned}\text{Volume} &= A \cdot \beta \quad \text{or} \quad V = \begin{vmatrix} t & t+1 & 2t+1 \\ 2t & 3t-1 & t \\ 1 & 3t & 1 \end{vmatrix} \\ &= (\alpha \times \gamma) \cdot \beta \\ &= [\alpha \ \gamma \ \beta]\end{aligned}$$

$$\begin{aligned}&= (-6t^2 - 2t + 1)(2t) + (t+1)(3t-1) \\ &\quad + (3t^2 - t - 1)(t)\end{aligned}$$

$$= -12t^3 - 4t^2 + 2t + 3t^2 + 3t - t - 1$$
$$+ 3t^3 - t^2 - t$$

$$= -9t^3 - 2t^2 + 3t - 1$$

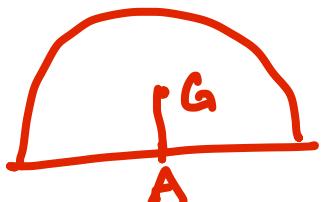
Rate of change of volume  $= \frac{dV}{dt}$

$$= -27t^2 - 4t + 3$$

$$\left(\frac{dV}{dt}\right)_{t=1} = -27 - 4 + 3 = -28$$

- 5d) A solid hemisphere rests in equilibrium on a solid sphere of equal radius. Determine the stability of the equilibrium in the two situations  
 (i) when the curved surface and (ii) when the flat surface of the hemisphere rests on the sphere.

### Question Bank SCE06 Qn- 1



Hemisphere  
 $CG : AG = \frac{3a}{9}$

#### (a) Curved surface on Sphere

$$AG = a - \frac{3a}{9} = \frac{5a}{9}$$

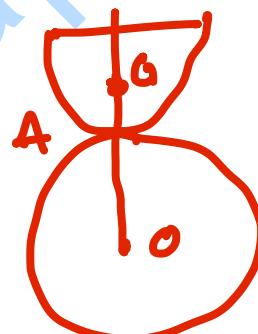
Radius of lower body  $R = a$

Radius of upper body  $r = a$

$$\frac{1}{R} + \frac{1}{r} = \frac{1}{a} + \frac{1}{a} = \frac{2}{a} = \frac{10}{5a}$$

$$\frac{1}{h} = \frac{8}{5a}$$

$$\frac{1}{R} + \frac{1}{r} > \frac{1}{h} \quad \text{Unstable}$$



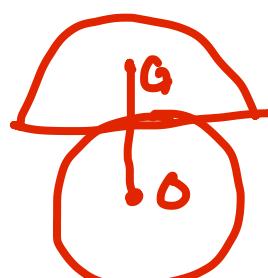
#### (b) Flat surface $r = \infty$

Radius of lower body  $R = a$

$$\frac{1}{R} + \frac{1}{r} = \frac{1}{a} + \frac{1}{\infty} = \frac{1}{a} = \frac{3a}{3a}$$

$$h = \frac{3a}{8} : CG \text{ of upper body}$$

$$\frac{1}{h} > \frac{1}{R} + \frac{1}{a} \rightarrow \frac{1}{h} = \frac{8}{3a}$$



- 5e) (i) Let  $C$  be a plane curve  $\bar{r}(t) = f(t)\hat{i} + g(t)\hat{j}$ , where  $f$  and  $g$  have second-order derivatives. Show that the curvature at a point is given by

$$K = \frac{|f'(t)g''(t) - g'(t)f''(t)|}{([f'(t)]^2 + [g'(t)]^2)^{3/2}}$$

What is the value of torsion  $\tau$  at any point of this curve?

$$\mathbf{r} = (f(t), g(t), 0)$$

$$\dot{\mathbf{r}} = (f'(t), g'(t), 0)$$

$$\ddot{\mathbf{r}} = [f''(t), g''(t), 0]$$

$$\dot{\mathbf{r}} \times \ddot{\mathbf{r}} = \begin{bmatrix} i & j & k \\ f'(t) & g'(t) & 0 \\ f''(t) & g''(t) & 0 \end{bmatrix}$$

$$= k [f'(t)g''(t) - f''(t)g'(t)]$$

$$|\dot{\mathbf{r}}|^2 = [f'(t)]^2 + [g'(t)]^2$$

$$K = \frac{|\dot{\mathbf{r}} \times \ddot{\mathbf{r}}|}{|\dot{\mathbf{r}}|^3} = \frac{[f'(t)g''(t) - f''(t)g'(t)]}{[f'(t)^2 + g'(t)^2]^{3/2}}$$

$$\dddot{\mathbf{r}} = [f'''(t), g'''(t), 0]$$

$$\mathcal{C} = \text{Torsion} = \frac{[\ddot{\gamma} \ddot{\dot{\gamma}} \ddot{\ddot{\gamma}}]}{|\dot{\gamma} \times \ddot{\gamma}|^2}$$

$$[\ddot{\gamma} \ddot{\dot{\gamma}} \ddot{\ddot{\gamma}}] = [\dot{\gamma} \times \ddot{\gamma}] \cdot [\ddot{\ddot{\gamma}}]$$

But  $\dot{\gamma} \times \ddot{\gamma} = [ ] \hat{k}$

$$= [ ] \hat{k} \cdot [ \epsilon'''(t) i + g'''(t) j + o \hat{k} ]$$

$$= [ ] \times 0 = 0$$

Torsion is zero

(ii) Show that the principal normals at two consecutive points of a curve do not intersect unless torsion  $\tau$  is zero.

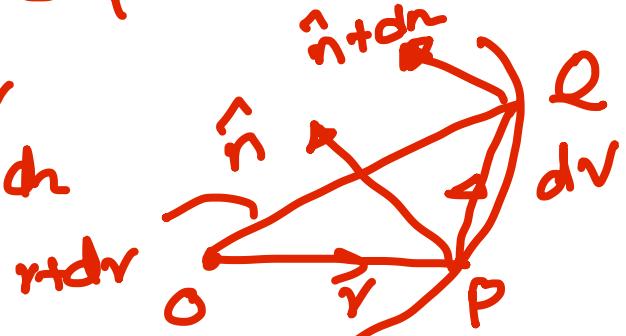
$P, Q$  be two consecutive pts on curve,

position vector is  $\vec{r}, \vec{r} + d\vec{r}$

Principal normal is  $\hat{n}$  &  $\hat{n} + dn$

Three vectors

$\hat{n}, \hat{n} + dn, dr$  lie  
on plane



$$[\hat{n}, \hat{n} + dn, dr] = 0$$

$$[\hat{n}, \hat{n}, dr] + [\hat{n}, dn, dr] = 0$$

$$\Rightarrow [\hat{n}, dn, dr] = 0$$

$$\Rightarrow \left[ \hat{n}, \frac{dn}{ds}, \frac{dr}{ds} \right] = 0$$

$$[\hat{n}, \hat{n}', r'] = 0$$

$$\begin{aligned} \hat{n}' &= \tau b - k t \\ r' &= t \end{aligned}$$

$$[\hat{n}, \tau b - k t, t] = 0$$

$$[\hat{n}, \tau b, t] - [\hat{n}, k t, t] = 0$$

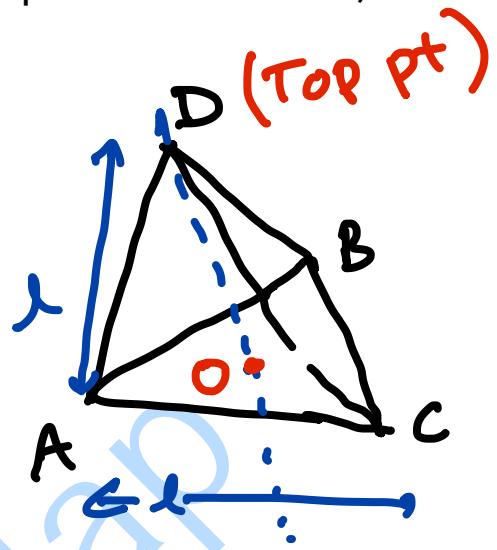
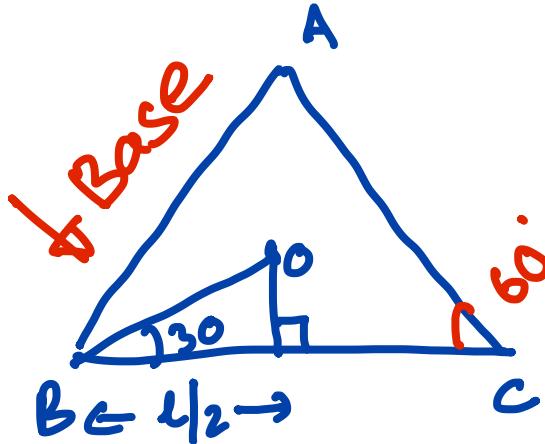
$$\tau [n b t] - k [n, t, t] = 0$$

$$\tau = 0$$

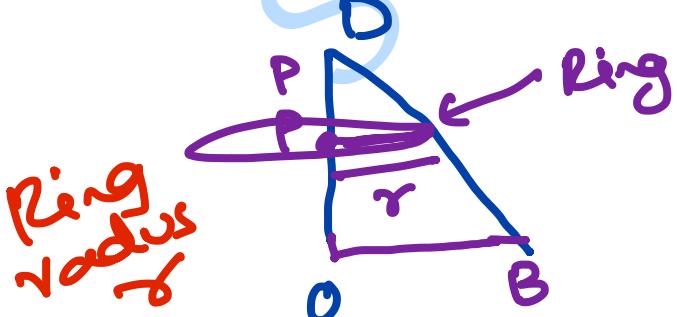
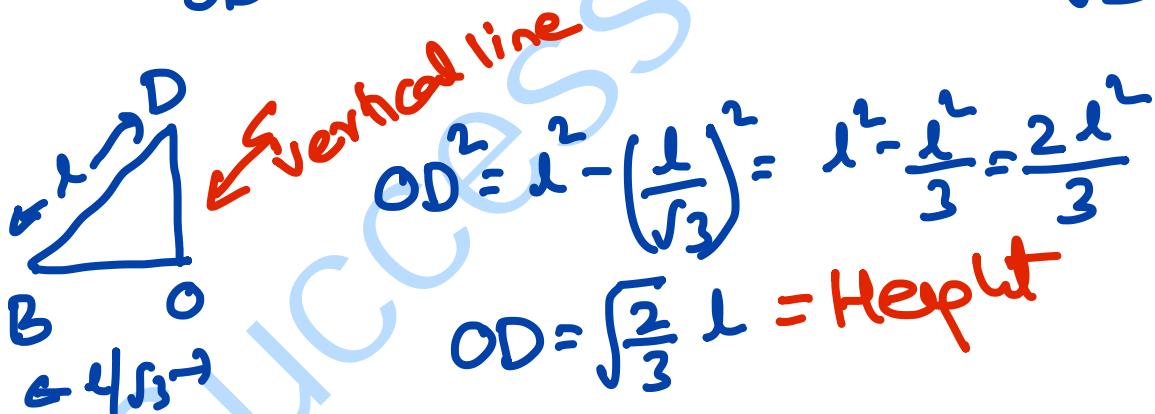
$$[n b t] = 1 \quad [n t t] = 0$$

Principal normal at two consecutive pt  
do not intersect unless  $\tau = 0$

- 6a) A regular tetrahedron, formed of six light rods, each of length  $l$ , rests on a smooth horizontal plane. A ring of weight  $W$  and radius  $r$  is supported by the slant sides. Using the principle of virtual work, find the stress in any of the horizontal sides.



$$\cos 30 = \frac{4/2}{OB} = \frac{\sqrt{3}}{2} \Rightarrow \frac{l}{OB} = \sqrt{3} \quad OB = \frac{l}{\sqrt{3}}$$



$$\frac{PD}{r} = \frac{OD}{OB}$$

$$PD = r \frac{OD}{OB} = r \frac{\sqrt{\frac{2}{3}} l}{l/\sqrt{3}}$$

$$= r \sqrt{2}$$

$$OP = OD - PD$$

$$= \sqrt{\frac{2}{3}} l - r \sqrt{2} = \text{Distance of Ring from Base}$$

Ring :  $W \times \delta P O$

Horizontal rod stress =  $3 \delta L \cdot T$

Virtual method

$$- W \delta P O + 3T \delta L = 0$$

$$- W \left( \sqrt{\frac{2}{3}} \right) \delta L + 3\delta L T = 0$$

$$W \sqrt{\frac{2}{3}} \times \frac{1}{3} = T$$

$$T = W \sqrt{\frac{2}{27}}$$

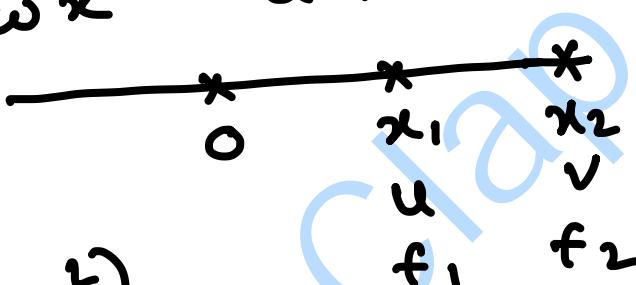
\* Soln is to be verified again

- 6b) A particle executes simple harmonic motion such that in two of its positions, velocities are  $u$  and  $v$ , and the two corresponding accelerations are  $f_1$  and  $f_2$ . For what value(s) of  $k$ , the distance between the two positions is  $k(v^2 - u^2)$ ? Show also that the amplitude of the motion is  $\frac{1}{f_2^2 - f_1^2} [(u^2 - v^2)(u^2 f_2^2 - v^2 f_1^2)]^{1/2}$

### Question Bank SCE02-On-10

$$\text{SHM: } v^2 = \omega^2(A^2 - x^2) \quad A \rightarrow \text{amp}$$

$$a = -\omega^2 x \quad a \rightarrow \text{acceleration}$$



$$\left[ \begin{array}{l} u^2 = \omega^2(A^2 - x_1^2) \\ v^2 = \omega^2(A^2 - x_2^2) \end{array} \right]$$

$$\left[ \begin{array}{l} f_1 = \omega^2 x_1 \\ f_2 = \omega^2 x_2 \end{array} \right]$$

$$v^2 - u^2 = \omega^2 [x_1^2 - x_2^2]$$

$$= \omega^2 [x_1 - x_2] [x_1 + x_2]$$

$$= \omega^2 (x_1 + x_2) (x_1 - x_2)$$

$$= (f_1 + f_2) (x_1 - x_2)$$

$$x_1 - x_2 = \frac{v^2 - u^2}{f_1 + f_2}$$

Add  $f_1 + f_2 = \omega^2(x_1 + x_2)$

Qn: what value of  $K$ , the distance b/w two position is  $K(v^2 - u^2)$

$$K = ? \quad x_1 - x_2 = K(v^2 - u^2) = \frac{(v^2 - u^2)}{f_1 + f_2}$$

$$\boxed{K = \frac{1}{f_1 + f_2}}$$

$$\begin{aligned} f_1 &= \omega x_1 \Rightarrow \\ f_2 &= \omega x_2 \Rightarrow \end{aligned} \quad \left. \begin{aligned} f_1 - f_2 &= \omega^2(x_1 - x_2) \\ &= \omega^2 \left( \frac{v^2 - u^2}{f_1 + f_2} \right) \end{aligned} \right\}$$

$$(f_1 + f_2)(f_1 - f_2) = \omega^2(v^2 - u^2)$$

$$f_1^2 - f_2^2 = \omega^2(v^2 - u^2)$$

$$\omega^2 = \frac{f_1^2 - f_2^2}{v^2 - u^2}$$

why  $x_1 - x_2 = \frac{v^2 - u^2}{f_1 + f_2}$   
proved above

$$\begin{aligned} \text{we have } u^2 &= \omega^2(A^2 - x_1^2) \\ &= \omega^2 \left( A^2 - \frac{f_1^2}{\omega^4} \right) \end{aligned}$$

$$x_1 = \frac{f_1}{\omega^2}$$

$$\frac{u^2}{\omega^2} = A^2 - \frac{f_1^2}{\omega^4}$$

$$A^2 = \frac{u^2}{\omega^2} + \frac{f_1^2}{\omega^4}$$

$$\frac{1}{\omega^2} = \frac{v^2 - u^2}{f_1^2 - f_2^2}$$

$$A^2 = u^2 \left( \frac{v^2 - u^2}{f_1^2 - f_2^2} \right) + f_1^2 \left( \frac{v^2 - u^2}{f_1^2 - f_2^2} \right)^2$$

$$= \frac{v^2 - u^2}{f_1^2 - f_2^2} \left[ u^2 + \frac{(v^2 - u^2)f_1^2}{f_1^2 - f_2^2} \right]$$

$$= \frac{v^2 - u^2}{f_1^2 - f_2^2} \left[ \frac{u^2 f_1^2 - u^2 f_2^2 + v^2 f_1^2 - u^2 f_1^2}{f_1^2 - f_2^2} \right]$$

$$= \frac{v^2 - u^2}{f_1^2 - f_2^2} \left[ \frac{v^2 f_1^2 - u^2 f_1^2}{f_1^2 - f_2^2} \right]$$

$$= \frac{1}{(f_1^2 - f_2^2)^2} (v^2 - u^2)(v^2 f_1^2 - u^2 f_2^2)$$

As per answer  $(f_1^2 - f_2^2)^2 = (f_2^2 - f_1^2)^2$

$$(v^2 - u^2)(v^2 f_1^2 - u^2 f_2^2) = (u^2 - v^2)(u^2 f_2^2 - v^2 f_1^2)$$

$$-1 \times -1 = 1$$

$$A = \frac{1}{f_2^2 - f_1^2} \left[ (u^2 - v^2)(u^2 f_2^2 - v^2 f_1^2) \right]^{1/2}$$

- 6c) (a) Find the second solution of the differential equation  $xy'' + (x - 1)y' - y = 0$  using  $u(x) = -e^{-x}$  as one of the solutions.

$$y = uv \quad u = -e^{-x}$$

$$\frac{du}{dx} = (-1)(-1)e^{-x} = e^{-x}$$

$$\frac{2}{u} \frac{du}{dx} = \frac{2}{-e^x} \times e^{-x} = -2$$

$$y'' + \left(\frac{x-1}{x}\right)y' - \left(\frac{1}{x}\right)y = 0$$

$$y'' + Py' + Qy = R \quad P = \frac{x-1}{x} \quad Q = -\frac{1}{x} \quad R = 0$$

$$P + \frac{2}{u} \frac{du}{dx} = \frac{x-1}{x} - 2 = 1 - \frac{1}{x} - 2 = -1 - \frac{1}{x} = -\left(1 + \frac{1}{x}\right)$$

$$\frac{d^2v}{dx^2} + \left(P + \frac{2}{u} \frac{du}{dx}\right) \frac{dv}{dx} = 0$$

$$\frac{dv}{dx} = q$$

$$\frac{dq}{dx} - \left(1 + \frac{1}{x}\right)q = 0 \quad \Rightarrow \quad \frac{dq}{q} = \left(1 + \frac{1}{x}\right)dx$$

$$\ln q = x + \ln x + \ln C$$

$$q = e^x \cdot xC = Cxe^x$$

$$\frac{dv}{dx} = Cxe^x$$

$$\begin{aligned}
 v &= c \int x e^x dx \\
 &= c \left[ x \int e^x - 1 \cdot \int 1 \cdot f e^x \right] dx \\
 &= c \left[ x e^x - e^x \right] = c(x-1)e^x
 \end{aligned}$$

$$\begin{aligned}
 y &= u v & u &= -e^{-x} \\
 &= c(x-1)e^x (-e^{-x}) = c(1-x)
 \end{aligned}$$

Second Soln is  $y = c(1-x)$

(b) Find the general solution of the differential equation  $x^2y'' - 2xy' + 2y = x^3 \sin x$  by the method of variation of parameters.

$$x^2y'' - 2xy' + 2y = x^3 \sin x$$

$$x = e^z \quad D_1 \equiv \frac{d}{dz} \quad (D_1(D_1-1) - 2D_1 + 2)y = 0$$

$$(D_1^2 - 3D_1 + 2)y = 0 \quad = (D_1-1)(D_1-2) = 0$$

$$D_1 = 2, 1$$

$$y_C = c_1 e^z + c_2 e^{2z}$$

$$= c_1 x + c_2 x^2$$

$$u = x \quad v = x^2 \quad u' = 1 \quad v' = 2x$$

$$W = \begin{vmatrix} u & v \\ u' & v' \end{vmatrix} = \begin{vmatrix} x & x^2 \\ 1 & 2x \end{vmatrix} = 2x^2 - x = x^2 \neq 0$$

$$PI = A u + B v$$

$$\text{Main eqn is } y'' - \frac{2y'}{x} + \frac{2}{x^2}y = x \sin x$$

$$= R$$

$$R = x \sin x$$

$$A = - \int \frac{v R}{W} dx \quad B = \int \frac{u R}{W} dx$$

$$\begin{aligned}
 A &= - \int \frac{(x^2)(x \sin x)}{x^2} dx = - \int x \sin x dx \\
 &= (-1) \left[ x(-\cos x) - \int (-\cos x) dx \right] \\
 &= (-1) \left[ -x \cos x + \sin x \right] \\
 &= x \cos x - \sin x
 \end{aligned}$$

$$\begin{aligned}
 B &= \int \frac{uR}{W} dx = \int \frac{x \cdot x \sin x}{x^2} dx = \int \sin x dx \\
 &= -\cos x
 \end{aligned}$$

*Success*

$$\begin{aligned}
 PI &= Au + Bu \\
 &= x^2 \cos x - x \sin x - x^2 \cos x \\
 &= -x \sin x
 \end{aligned}$$

$$u = x \quad v = x^2$$

$$z = C_1 x + C_2 x^2 - x \sin x$$

- 7a) State uniqueness theorem for the existence of unique solution of the initial value problem  $\frac{dy}{dx} = f(x, y)$ ,  $y(x_0) = y_0$  in the rectangular region  $R: |x - x_0| \leq a, |y - y_0| \leq b$ . Test the existence and uniqueness of the solution of the initial value problem  $\frac{dy}{dx} = 2\sqrt{y}$ ,  $y(1) = 0$ , in a suitable rectangle  $R$ . If more than one solution exists, then find all the solutions.

Existence Thm: If  $f$  is continuous function in open rectangle  $R = \{(x, y) \mid a < x < b, c < y < d\}$  that contains point  $(x_0, y_0)$ , then initial value problem  $y' = f(x, y)$   $y(x_0) = y_0$  has at least a solution in some open sub-interval of  $(a, b)$  which contains the point  $x_0$ .

Uniqueness Thm: If  $f$  and  $f_y$  are continuous function in open rectangle  $R = \{(x, y) \mid a < x < b, c < y < d\}$  that contains a point  $(x_0, y_0)$ , then the initial value problem  $y' = f(x, y)$   $y(x_0) = y_0$  has a unique solution on some open sub-interval of  $(a, b)$  which contains the point  $x_0$ .

→ It provide info about existence of soln to Initial value problem, but does not state how to find solutions or find the open interval

→ It does not provide info about how many solutions may have.

$$\rightarrow \frac{dy}{dx} = 2\sqrt{y} = f(x, y) \quad y(1) = 0$$

$$f'(y) = 2\left(\frac{1}{2\sqrt{y}}\right) = \frac{1}{\sqrt{y}}$$

$f'(y)$  is not continuous at  $y=0$

Thm:  $f$  &  $f'(y)$  to be continuous then uniqueness

Here  $f'(y)$  is not continuous at  $y=0$   
So No - Unique Soln

$$\rightarrow \text{other solns: } \frac{dy}{dx} = 2\sqrt{y}$$

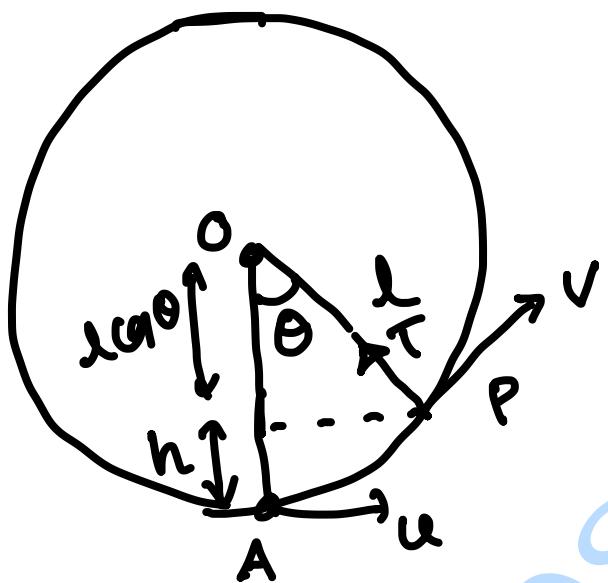
$$\frac{dy}{\sqrt{y}} = 2dx = 2\sqrt{y} = 2x + C$$

But  $y(1) = 0 \Rightarrow x=1, y=0 \Rightarrow C=-2$

$$\text{Soln } 2\sqrt{y} = 2x - 2 \Rightarrow \underline{\sqrt{y} = x - 1}$$

- 7b) A heavy particle hanging vertically from a fixed point by a light inextensible string of length  $l$  starts to move with initial velocity  $u$  in a circle so as to make a complete revolution in a vertical plane. Show that the sum of tensions at the ends of any diameter is constant.

UPSC - 1998



A: velocity  $u$

$$\frac{1}{2}mu^2 = \frac{1}{2}mv^2 + mgh$$

$$h = l - l\cos\theta$$

$$= l(1 - \cos\theta)$$

$$u^2 = v^2 + 2gl(1 - \cos\theta)$$

$$v^2 = u^2 - 2gl(1 - \cos\theta)$$

$g\sin\theta$

$$T - mg\cos\theta = \frac{mv^2}{l}$$

$$T = mg\cos\theta + \frac{mv^2}{l}$$

$$= mg\cos\theta + \frac{m(u^2 - 2gl(1 - \cos\theta))}{l}$$

$$= mg\cos\theta + \frac{mu^2}{l} - 2mg(1 - \cos\theta)$$

$$= \frac{mu^2}{l} + mg\cos\theta - 2mg + 2mg\cos\theta$$

$$T = \frac{mu^2}{l} - 2mg + 2mg\cos\theta$$

$$[T]_{\text{at } \theta} = \frac{mu^2}{l} - 2mg + 2mg\cos\theta$$

At other end of diameter  
 $\theta \rightarrow \theta + \pi$

$$\cos(\theta + \pi) = -\cos\theta$$

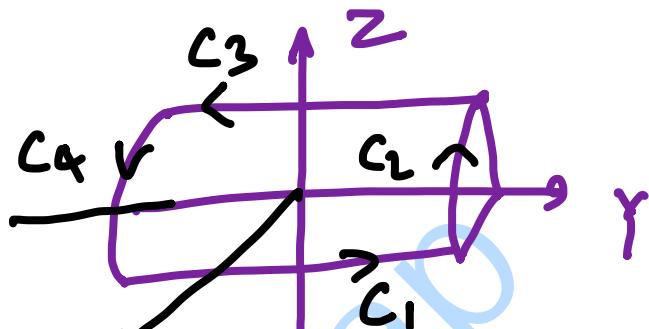
$$[T]_{\text{at } \theta + \pi} = \frac{mu^2}{l} - 2mg - 2mg\cos\theta$$

$$[T]_{\text{at } \theta} + [T]_{\text{at } \theta + \pi} = \frac{2mu^2}{l} - 4mg \\ = \text{constant}$$

- 7c) State Stokes' theorem and verify it for the vector field  $\vec{F} = xy\hat{i} + yz\hat{j} + zx\hat{k}$  over the surface  $S$ , which is the upwardly oriented part of the cylinder  $z = 1 - x^2$ , for  $0 \leq x \leq 1, -2 \leq y \leq 2$ .

**Repeated UPSC Qn - UPSC-CSE-2020**

$$\mathbf{F} = xy\hat{i} + yz\hat{j} + zx\hat{k}$$



$$\nabla \times \mathbf{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xy & yz & zx \end{vmatrix} = -y\hat{i} - z\hat{j} - x\hat{k}$$

$$g(x, y, z) = z + x^2 - 1 = 0$$

$$\hat{n} = \frac{\nabla g}{|\nabla g|} = \frac{2x\hat{i} + \hat{k}}{\sqrt{4x^2 + 1}}$$

$$I = \iint_S (\nabla \times \mathbf{F}) \cdot \hat{n} \, dS = \iint_S \frac{-2xy - x}{\sqrt{4x^2 + 1}} \, dS$$

$$dS = \frac{dx dy}{|\hat{n} \cdot \hat{k}|} = \sqrt{4x^2 + 1} \, dx dy$$

$$I = \iint_S (-2xy - x) \frac{1}{\sqrt{4x^2 + 1}} \times \sqrt{4x^2 + 1} \, dx dy$$

$$\begin{aligned}
 &= \int_{x=0}^{x=1} \int_{y=-2}^{y=2} (-2xy - x) dy dx \\
 &= \int_{x=0}^{x=1} \left[ -xy^2 - xy \right]_{-2}^2 dx = \int_0^1 -4x dx \\
 &\quad = \underline{\underline{-2}}
 \end{aligned}$$

Line Integral  $\oint_C = \int_{C_1} + \int_{C_2} + \int_{C_3} + \int_{C_4}$

$$F \cdot dV = xy dx + yz dy + zx dz$$

$$C_1 : x=1 \ z=0 \ dx=0 \ dz=0$$

$$F \cdot dV = 0 \Rightarrow \int_{C_1} = 0$$

$$C_2 : y=2 \ z=1-x^2 \ dy=0 \ dz=-2x dx$$

$$\begin{aligned}
 F \cdot dV &= 2x dx + 0 + x(1-x^2)(-2x dx) \\
 &= 2x - 2x^3 + 2x^4 dx
 \end{aligned}$$

$$\int_{C_2} = \int_1^0 (2x - 2x^3 + 2x^4) dx = \frac{-11}{15}$$

$$C_3 : x=0 \ z=1 \ dx=0 \ dz=0$$

$$\int_{C_3} 4 dy = \int_2^{-2} 4 dy = 0$$

$$C_4 : y=-2 \ z=1-x^2 \ dy=0 \ dz=-2x dx$$

$$\int_{C_4} (-2x - 2x^3 + 2x^4) dx = -19/15$$

$$\oint F \cdot dV = 0 - 11/15 + 0 - 19/15 = \underline{\underline{-2}}$$

Project

8a) Using Laplace transform, solve the initial value problem

$$y'' + 2y' + 5y = \delta(t - 2), y(0) = 0, y'(0) = 0$$

where  $\delta(t - 2)$  denotes the Dirac delta function.

$$y'' + 2y' + 5y = \delta(t - 2)$$

$$L(y'') + 2L(y') + 5L(y) = L\{\delta(t - 2)\}$$

$$p^2 L(y) - p y(0) - y'(0) + 2[pL(y) - y(0)] + 5L(y) = L\{\delta(t - 2)\}$$

$$p^2 L(y) + 2pL(y) + 5L(y) = e^{-2p}$$

$$(p^2 + 2p + 5)L(y) = e^{-2p}$$

$$L(y) = \frac{e^{-2p}}{p^2 + 2p + 5} = \frac{e^{-2p}}{(p+1)^2 + 4}$$

Take inverse

$$L^{-1}\left(\frac{1}{(p+1)^2 + 4}\right) = e^{-t} \sin 2t$$

Time shifting property

$$L^{-1}\{e^{-as} F(s)\} = u(t-a)f(t-a)$$

$$y(t) = u(t-2)e^{-(t-2)} \sin(2(t-2))$$

8b) Using Gauss divergence theorem, evaluate the integral

$$\iint_S (y^2\hat{i} + xz^3\hat{j} + (z-1)^2\hat{k}) \cdot \hat{n} dS$$

over the region bounded by the cylinder  $x^2 + y^2 = 16$  and the planes  $z = 1$  and  $z = 5$ .

$$\iint_S \mathbf{F} \cdot \hat{n} dS = \iiint_V (\nabla \cdot \mathbf{F}) dV$$

$$\mathbf{F} = y^2\hat{i} + xz^3\hat{j} + (z-1)^2\hat{k}$$

$$\nabla \cdot \mathbf{F} = 0 + 0 + 2(z-1)$$

$$I = \iiint_V (\nabla \cdot \mathbf{F}) dV = \iiint_V 2(z-1) dV$$

$$= \iiint_V 2(z-1) dz dx dy$$

$$= \iiint_V 2(z-1) \rho d\rho d\theta dz$$

$$= \left[ \int_{\rho=0}^{\rho=4} \rho d\rho \right] \left[ \int_{\theta=0}^{2\pi} d\theta \right] \int_{z=1}^{z=5} 2(z-1) dz$$

$$= \frac{\rho^2}{2} \Big|_0^4 \times 2\pi \times (z-1)^2 \Big|_1^5$$

$$= 8 \times 2\pi \times [4^2 - 0] = 16\pi \times 16$$

$$= 256\pi$$

Cylindrical  
Coord  
System

- 8c) A particle moves with a central acceleration  $\mu \left( \frac{3}{r^3} + \frac{d^2}{r^5} \right)$  being projected from a distance  $d$  at an angle  $45^\circ$  with a velocity equal to that in a circle at the same distance. Prove that the time it takes to reach the centre of force is  $\frac{d^2}{\sqrt{2}\mu} \left( 2 - \frac{\pi}{2} \right)$

$$u = \frac{1}{\sqrt{v}} \quad \text{central acceleration } P = \mu \left( \frac{3}{r^3} + \frac{d^2}{r^5} \right)$$

$v$ : velocity in a circle at distance  $d$

$$\frac{v^2}{d} = [P]_{r=d} = \mu \left( \frac{3}{d^3} + \frac{d^2}{d^5} \right) \quad a=d$$

$$v^2 = \frac{4\mu}{d^2} \quad v = \frac{2\sqrt{\mu}}{d}$$

Diff eqn

$$h^2 \left[ u + \frac{du}{d\theta^2} \right] = \frac{P}{u^2} = \frac{\mu}{u^2} \left[ 3u^3 + d^2 u^5 \right]$$

$$= \mu \left( 3u + d^2 u^3 \right)$$

Multiply both side by  $2 \frac{du}{d\theta}$  & integrating

$$v^2 = h^2 \left[ u^2 + \left( \frac{du}{d\theta} \right)^2 \right] = \mu \left( 3u^2 + \frac{d^2}{2} u^4 \right) + A$$

Initial  $r=d$   $u=1/d$   $v=2\sqrt{\mu}/d$   $\theta=45^\circ$

$$P = v \sin \phi = d \sin \frac{\pi}{4} = \frac{d}{\sqrt{2}}$$

$$\frac{1}{P^2} = u^2 + \left(\frac{du}{d\theta}\right)^2 = \frac{2}{d^2}$$

$$\frac{4H}{d^2} = h^2 \cdot \frac{2}{d^2} = H \left( \frac{3}{d^2} + \frac{d^2}{2d^4} \right) + A$$

$$h^2 = 2H \quad A = \frac{H}{2d^2}$$

Putting  $h^2, A$  in eqn

$$2H \left[ u^2 + \left(\frac{du}{d\theta}\right)^2 \right] = H \left( 3u^2 + \frac{d^2}{2} u^4 \right) + \frac{H}{2d^2}$$

$$2 \left(\frac{du}{d\theta}\right)^2 = u^2 + \frac{d^2}{2} u^4 + \frac{1}{2d^2}$$

$$u = \frac{1}{r} \quad \frac{du}{d\theta} = -\frac{1}{r^2} \frac{dr}{d\theta}$$

$$\frac{2}{r^4} \left(\frac{dr}{d\theta}\right)^2 = \frac{1}{r^2} + \frac{d^2}{2r^4} + \frac{1}{2d^2}$$

$$4d^2 \left(\frac{dr}{d\theta}\right)^2 = 2d^2 r^2 + d^4 + r^4 = (r^2 + d^2)^2$$

$$\frac{dr}{d\theta} = -\frac{r^2 + d^2}{2d}$$

negative sign because  
 $r$  decrease when  $\theta$   
increase

$$h = r^2 \frac{d\theta}{dt} = r^2 \frac{d\theta}{dr} \cdot \frac{dr}{dt}$$

$$\sqrt{2H} = -r^2 \frac{2d}{r^2 + d^2} \cdot \frac{dr}{dt}$$

$$dt = -\frac{2d}{\sqrt{2H}} \frac{r^2 dr}{r^2 + d^2}$$

$$t_1 = \frac{-2d}{\sqrt{2H}} \int_{r=d}^0 \frac{r^2 dr}{r^2 + d^2}$$

$$= \frac{-2d}{\sqrt{2H}} \int_d^0 \left[ 1 - \frac{d^2}{r^2 + d^2} \right] dr$$

$$= \frac{-2d}{\sqrt{2H}} \left[ r - d \tan^{-1} \frac{r}{d} \right]_d^0$$

$$= \frac{-2d}{\sqrt{2H}} \left[ (0 - d \tan^{-1} 0) - (d - d \tan^{-1} \frac{d}{d}) \right]$$

$$= \frac{2d}{\sqrt{2H}} \left[ d - d \cdot \frac{\pi}{4} \right]$$

$$= \frac{d^2}{\sqrt{2H}} \left[ 2 - \frac{\pi}{2} \right]$$